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|  | United Nations | ECE/TRANS/WP.29/GRBP/2025/3 | |
| _unlogo | **Economic and Social Council** | | Distr.: General  29November 2024  Original: English |

**Economic Commission for Europe**

Inland Transport Committee

**World Forum for Harmonization of Vehicle Regulations**

**Working Party on Noise and Tyres**

**Eighty-first session**

Geneva, 18–21 February 2025

Item 7 of the provisional agenda

**Regulatory Fitness for Automated Driving Systems**

**Proposal for Supplement 2 to the 02 series of amendments to UN Regulation No. 138**

**Submitted by the Task Force on Automated Vehicles Regulation Screening[[1]](#footnote-2)\***

The text reproduced below was prepared by the Task Force on Automated Vehicles Regulation Screening (TF AVRS) in order to make the requirements of UN Regulation No. 138 fit for approval of Automated Driving Systems. The modifications to the current text of the UN Regulation are marked in bold for new or strikethrough for deleted characters.

**I. Proposal**

*Table of Content, Annexes,* amend to read:

“Annexes

1 Communication 14

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**5 Provisions for Automated Driving Systems…………………………………………………. 43”**

*Paragraphs 2.7. and 2.8.,* amend to read:

“2.7."*Mass in running order*" means the mass of the vehicle, with its fuel tank(s) filled to at least 90 % of its or their capacity/ies, ~~including the mass of the driver (75 kg)~~, of the fuel and liquids, fitted with the standard equipment in accordance with the manufacturer’s specifications and, when they are fitted, the mass of the bodywork, the cabin, the coupling and the spare wheel(s) as well as the tools, **including the mass of the driver (75 kg) if there is a driver’s seat in the vehicle.**

2.8. "*Pause function*" means a mechanism to enable the driver **or ADS (as defined in paragraph 2.13.)** to halt the operation of an AVAS.”

*Insert new paragraphs 2.13. to 2.16.* to read:

***“2.13. “Automated Driving System (ADS)”* means the vehicle hardware and software that are collectively capable of performing the entire Dynamic Driving Task (DDT) on a sustained basis.1**

***2.14. “Dynamic Driving Task (DDT)”* means the real-time operational and tactical functions required to operate the vehicle.**

***2.15. “Bi-directional vehicle” means a vehicle that can operate in two opposite forward directions.***

***2.16. “Forward direction” (of a vehicle) means a direction that is intended to be used as main travelling direction of the vehicle.***

*Paragraph 2.13. (former),* renumber to 2.17. and amend to read:

***“2.17.****~~2.13~~* Symbols and abbreviated terms and the paragraph in which they are first used.”

*Insert a new footnote 1* to read:

“1 **This definition is based on SAE J3016 and ISO/PAS 22736 (Taxonomy and Definitions for Terms Related to Driving Automation Systems for On-Road Motor Vehicles). These standards define levels of driving automation based on the functionality of the driving automation system feature as determined by an allocation of roles in DDT and DDT fallback performance between that feature and the (human) user (if any). The term “Automated Driving System” is used specifically to describe a Level 3, 4, or 5 driving automation system.”**

*Paragraph 6.2.5.,* amend to read:

“6.2.5. ~~Driver selectable~~**Available** AVAS sounds

The vehicle manufacturer may define ~~alternative~~ **different available** sounds~~which can be accepted by the driver~~. Each of these sounds shall be in compliance and approved with the provisions in paragraphs 6.2.1. to 6.2.4.

The compliance with paragraph 6.2.8., Tables 2a and 2b of non-tested sound modes during type approval in respect to Annex 3, paragraph 3.2.3. shall be confirmed by the manufacturer declaration (Annex 4).”

*Annex 1, Addendum to the communication form, item 1.2.2.*, amend to read:

“1.2.2. No. of **available** AVAS sounds (1/2/3/…)”

*Annex 3, paragraph 3.3.1*, amend to read:

“3.3.1. General

For each operating condition, the vehicle can be tested either indoor or outdoor.

For constant speed and reversing tests the vehicle may be tested either in motion or in simulated operating condition. For simulated vehicle operation, signals shall be applied to the vehicle to simulate actual in-use operation.

If the vehicle is equipped with an internal combustion engine, it shall be turned off.

**In the case of bi-directional vehicles, the measurements shall be conducted separately for each front plane of the vehicle and the requirements for forward driving apply to both forward directions.**

**If no reverse mode is available, the requirements of table 2b for reverse driving do not apply.**

**If one or more reverse modes are available, the requirements of table 2b for reverse driving apply to each of them and additional tests for reverse driving shall be conducted accordingly.”**

*Insert a new Annex 5* to read:

“Annex 5

Provisions for vehicles equipped with an Automated Driving Systems (ADS)

**Definition of subcategories of vehicles equipped with an ADS as contained in the Consolidated Resolution on the Construction of Vehicles (R.E.3):**

**Subcategory X: Intended to be used without a driver and designed to carry occupants.**

**Subcategory Y: Intended to be used without a driver and not designed to carry occupants.**

**Subcategory Dual mode: Intended to be controlled either by a driver or by the ADS.**

* + - 1. **Test procedures for vehicles equipped with an ADS**
  1. **Vehicles in subcategory Dual mode can be tested in the manual driven condition when the manufacturer declares that there is no significant difference between the two modes with regards to this regulation.**
  2. **Test procedure for vehicles in subcategories X and Y**

**(a) When performing Methods (A) or (C), either the vehicle or the track or both shall be prepared to enable the test vehicle to fulfil the test conditions prescribed in Annex 3 of this regulation. Examples of preparations that could be used:**

**(i) the track might be prepared with additional lines, traffic signs and other measures.**

**(ii) the vehicle might have a test mode, be controlled by an operator in the vehicle or remote to drive the vehicle on the track.**

**(b) When performing Methods (B) or (D) the simulated speed signal shall be used as described in Annex 3 of this Regulation.”**

**II. Justification**

The objective of TF AVRS is to amend the UN Regulations in the purview of GRBP, where necessary, to make it possible for Automated Driving Systems (ADS) to meet the requirements of these Regulations. TF AVRS will not add new requirements to the UN Regulations in their current scope.

1. \* In accordance with the programme of work of the Inland Transport Committee for 2025 as outlined in proposed programme budget for 2025 (A/79/6 (Sect. 20), table 20.6), the World Forum will develop, harmonize and update UN Regulations in order to enhance the performance of vehicles. The present document is submitted in conformity with that mandate. [↑](#footnote-ref-2)