Status Report

Task Force

Automated Vehicles Regulatory Screening

(TF-AVRS)

of UN Regulations and GTRs under responsibility of

GRSP

Task Force on Automated Vehicles Regulatory Screening Facts and task:

- Contracting parties and the industry need a regulatory environment for new vehicle concepts with highly automated driving functions (ADS) above SAE Level 3.
- This also means that existing, non-ADS regulations can be applied to such vehicles.

1st step, check:

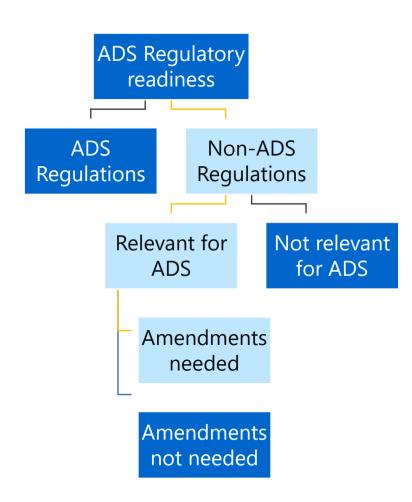
• which existing regulations are relevant for automated vehicles? Which ones need to be amended before they are applicable to vehicles with ADS?

Original mandate (given by WP.29 186th session):

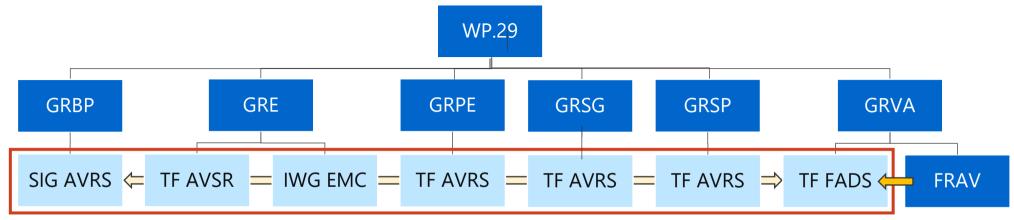
- Scan all 167 UN Regulations and 23 Global Technical Regulations
- Expected at 190th session in June 2023: Report, summary and details for each Regulation, instructions for drafting amendments

Quelle:

Informal document GRVA-17-29
 17th GRVA, 25–29 September 2023



Task Forces:



Expert groups on regulatory fitness for ADS

Quelle:

Informal document GRVA-17-29
 17th GRVA, 25–29 September 2023

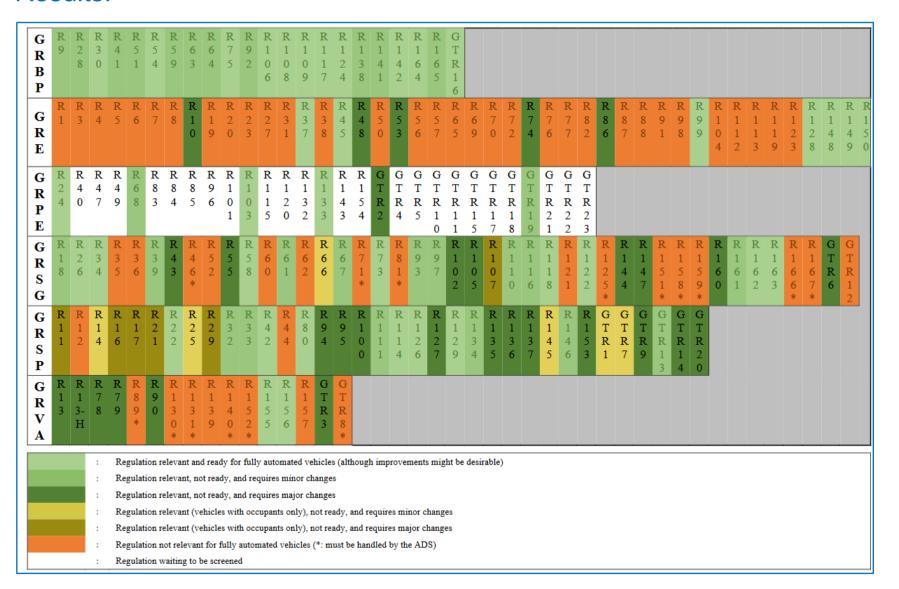
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Report to WP.29 (WP29/2023/86) (re-submitted with translation as GRVA/2023/18):

- Contains global results, summary sheets for each screened Regulations (see next slide)
- Adopted by WP.29
- Will be updated to reflect the continued progress of the groups

	Major amendments needed	See OBJECTIVE 3				
Readiness:	Tregulation Female					
Regulation relevant for fully automated vehicles			See OBJECTIVE 1 See OBJECTIVE 2			
		Yes	No			
Outcome of the review						
Notes	Additional comments from the screening task force.					
Summary of recommended changes Possible (non-exhaustive) changes that could contribute to making the Regulation applicable to automated vehicles.						
Content to be covered by (potential) ADS Regulation	Concepts related to the Regulation, and which handled by the ADS.	Specifics for vehicles without occupants		Any provisions that have a particular effect on vehicles not equipped that are not designed to carry occupants. Example: a "passenger compartment" does not exist in a vehicle that is not designed to carry occupants.		
Content relevant for vehicles equipped with an ADS	Examples of provisions particularly relevant when the driving task is carried out by an ADS, whether the vehicle be "dual mode", without manual driving capabilities or not designed to carry occupants.		Specifics for vehicles without manual driving capabilities		Any provisions that have a particular effect on vehicles not equipped with manual driving capabilities. Example: a "driver's seat" still exists in a dual-mode vehicle, but not in a vehicle without manual driving capabilities.	
Content of existing Regulation	Short explanation of the purpose of the Regulations or the provisions contained therein.		Specifics for dual- mode vehicles		Any provisions that have a particular effect on dual-mode vehicles, e.g. because of interactions between manual driving capabilities and a driving task carried out by the ADS, or because of issues that may occur during transitions between manual and automated modes.	
Regulation No. Scope	supplement used during the screening process. Categories of vehicles (as defined in R.E.3 or S.R.1) which the Regulation is applicable to.		Date of revi	ew	Date of the creation of this one-page summary	
	The number and title of the Regulation, including the exact Series of amendments and					

Screening results for individual Regulations and GTRs



Subsidiary Working Party	Regulations to be amended in priority
GRBP	R9, R28, R51, R138, R165
GRE	R10, R48
GRPE	To be decided after all Regulations have been screened.
GRSG	R43, R107, R160, R.E.3, S.R.1
GRSP	R11, R14, R16, R 17, R 21, R29, R94, R95, R100
GRVA	R13, R13-H, R79

List of Regulations & GTRs to amend in priority

Theme	Related keywords					
Human person	Driver Rider	Passenger	Person	Occupant	Crew (member)	
Areas within the vehicle	Cockpit Driver's compartment Driving cab	Passenger compartment				
Body Parts	Hand Foot Arm Etc.					
Manual action	Lever Button Handle Switch	Push Pull Press Rotate	Force Muscular (energy)	Reach Accessible	Manual	
T7: ·	TT 11.1	0 1	T11	3.6 %		

List of relevant keywords

be relevant to maintain basic performance tests for Regulations on braking or steering in the interest of ensuring the compliance of the automated vehicle to these existing performance requirements.

4. Dual-mode interactions

29. Dual-mode vehicles may be equipped with several features, which might only be relevant in manual mode, especially driver assistance or active safety features. If those features are suspended when switching from manual to automated mode, their behaviour when switching again to manual mode should be the object of clear provisions, supporting the driver to safely regain control of the vehicle, also for the case when transitions only occur while the vehicle is stationary.

Test mode

30. Many Regulations contain testing provisions which must be performed on a testing bench or a test track. In both cases, automated vehicles without manual driving capabilities should be able to perform the exact test scenarios described in the Regulation. While there are no requirements at this stage on how this can be achieved, one potential solution is for the manufacturer to equip their vehicles with a test mode, which would allow any specific driving scenario to be generated by a Type Approval Authority or Technical Service. Special

List of high-level issues

Next steps, after presentation at the June 2023 WP.29 session:

New mandate

- All groups may start drafting amendments to proposed "priority Regulations"
- The groups shall present a timeline for amending relevant regulations at WP.29 in March 2024
- Coordination between groups shall continue for common definitions, translations and solutions to cross-GR issues
- GRSG and GRVA should coordinate the work on categories for automated vehicles and report on the status of work to AC.2 and WP.29 in November 2023.

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Next steps, after presentation at the June 2023 WP.29 session:

GR übergreifende Aufgaben

(Sub)categories for automated vehicles

Test mode

Dual-mode interactions

etc.

Einheitliche Definitionen

Based on FRAV definitions

Currently drafting the smallest possible list of needed definitions (example see next slide)

Einheitliche Umsetzung

First draft (UN-R 48) transmitted to the other groups

Task Force on Automated Vehicles Regulatory Screening Next steps, after presentation at the June 2023 WP.29 session:

Definition dependencies (from FRAV-43-04rev4)

Example: a definition such as "maximum design speed of the vehicle" needs to be changed to introduce the maximum speed supported by the **ODD**.

Operational Design Domain

Operating conditions under which an **ADS feature** is specifically designed to function.

ADS feature

An application of **ADS** hardware and software designed specifically for use within an ODD.

Automated Driving System

The hardware and software that are collectively capable of performing the entire **DDT** [...]

Operational function

A capability to control the realtime motion of the vehicle.

Tactical function

A capability to perceive the vehicle environment [...]

Dynamic Driving Task

The real-time **operational and tactical functions** required to operate [...]

These definitions should not have to be added to each relevant Regulation

The groups would welcome a central document at the WP.29 level

FADS will consult FRAV for missing useful definitions (dual-mode vehicle, etc.)

Source:

Informal document GRVA-17-29 17th GRVA, 25–29 September 2023

Results of the meeting of the TF Leader TF AVRS of all GR's, Paris, 16./17.10.2023:

JOINT STATEMENT OF THE WP.29 EXPERT GROUPS ON REGULATORY FITNESS FOR AUTOMATED DRIVING SYSTEMS

REGARDING THE

ESTABLISHMENT OF A TASK FORCE ON CATEGORIES FOR AUTOMATED VEHICLES

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Results of the meeting of the TF Leader TF AVRS of all GR's, Paris, 16./17.10.2023:

THE WP.29 EXPERT GROUPS ON REGULATORY FITNESS FOR AUTOMATED DRIVING SYSTEMS (GRBP SIG AVRS, GRE IWG EMC, GRE TF AVSR, GRPE TF AVRS, GRSG TF AVRS, GRSP TF AVRS, GRVA TF FADS),

after convening in Paris on 16 and 17 October 2023 and acknowledging the reports from the subsidiary Working Parties on general safety (GRSG) and automated and connected vehicles (GRVA) of the World Forum,

understanding that a task force regarding the definition of categories for automated vehicles is to be established as a collaborative effort between GRSG and GRVA, and will be co-led by a representative from either subsidiary Working Party,

striving to contribute to the integration of automated vehicles into the regulatory framework of WP.29 and

concerned that although the International Organisation of Vehicle Manufacturers (OICA) has offered their services as secretary of this future task force, no Contracting Party to the 1958 Agreement or to the 1998 Agreement has come forward to lead this important group,

Results of the meeting of the TF Leader TF AVRS of all GR's, Paris, 16./17.10.2023:

REQUEST ALL CONTRACTING PARTIES TO SHOW THEIR COMMITMENT TO THIS UPCOMING WORK AND TO CONSIDER THE FOLLOWING PRINCIPLES.

- 1. Vehicle categories classify vehicles according to their typical usage and common characteristics, allowing their inclusion in (or exclusion from) the scope of individual UN Regulations, Global Technical Regulations, and specific requirements within these Regulations. WP.29 recognized the urgency to consider automated vehicles and their classification before March 2024.
- 2. Categories for automated vehicles are also needed for administrative considerations such as vehicle registration, traffic rules and their enforcement, taxation, and road traffic safety statistics.
- 3. Given the complexity that vehicle categories represent, the number of stakeholders involved across disciplines, and their implications for both the 1958 and the 1998 Agreement, the expert groups believe that work should begin immediately with a first meeting in January 2024, with a first report to WP.29 in March 2024

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Results of the meeting of the TF Leader TF AVRS of all GR's, Paris, 16./17.10.2023:

REQUEST ALL CONTRACTING PARTIES TO SHOW THEIR COMMITMENT TO THIS UPCOMING WORK AND TO CONSIDER THE FOLLOWING PRINCIPLES.

- 4. The co-chairs of the task force should represent GRSG and GRVA respectively, and the 1958 and 1998 Agreements should both be equally represented in its leadership.
- 5. Understanding how categories of vehicles can affect national and regional laws, the expert groups invite stakeholders from all affected Contracting Parties—including Regional Economic Integration Organisations—to strongly contribute to this work. Other stakeholders from international organisations and the industry should also be consulted.
- 6. Categories of vehicles are relevant to international and national activities beyond the World Forum. The task force should therefore gather not only experts with a strong technical expertise, but all stakeholders with a direct interest in the evolution of vehicle categories.

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Results of the meeting of the TF Leader TF AVRS of all GR's, Paris, 16./17.10.2023:

REQUEST ALL CONTRACTING PARTIES TO SHOW THEIR COMMITMENT TO THIS UPCOMING WORK AND TO CONSIDER THE FOLLOWING PRINCIPLES.

- 7. The redefinition or addition of categories should be as simple as possible and limited to what is necessary. Furthermore, new subcategories represent a lower administrative impact than new categories. Finally, maintaining existing categories is less complex than a complete redefinition of all categories.
- 8. The updated categories should be technologically neutral and tackle all relevant use cases for automated vehicles transporting passengers, goods, a combination of both, or neither. This includes vehicles also equipped with manual controls, those which are not designed to carry human occupants and those which are also designed for off-road operation.

THE EXPERT GROUPS ON REGULATORY FITNESS FOR AUTOMATED DRIVING SYSTEMS, CLOSELY INVOLVED WITH THE TECHNICAL IMPACT OF CATEGORIES ON UN REGULATIONS AND GTRS, PLEDGE TO OFFER THEIR SUPPORT TO THE UPCOMING TASK FORCE

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Additional task: New vehicle (sub)-categories





Vehicle categorization under R.E.3

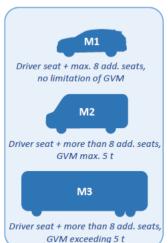
New sub categories for Automated Vehicles (AV's)

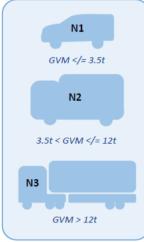
Subcategory A .. Driverless Vehicles with ADS"

Designed primarily for the carriage of people Designed primarily for the carriage of goods

Subcateaory D "Dual Mode vehicles" Designed primarily for the carriage of people Designed primarily for the carriage of goods

Subcateaories X & Y "Low speed driverless AV's"

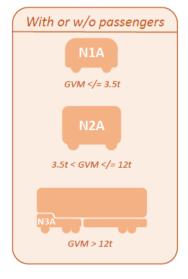








be carried over





Source: OICA/CI FPA proposal GRVA-17-37

Vehicles which can be driven manually under nominal conditions

Additional task: New vehicle (sub)-categories





Categories according to Consolidated Resolution R.E.3

Required amendments to existing Definitions:

2.2.	Category M - Power-driven vehicles having at least four wheels and used for the carriage of passengers					
2.2.1.	"Category M1":	Vehicles used for the carriage of passengers and comprising not more than eight nine seats in addition to the driver's seat.				
2.2.2.	"Category M2":	Vehicles used for the carriage of passengers, comprising more than eight nine seats in addition to the driver's seat or designed to carry standing passengers, and having a maximum mass not exceeding 5 tonnes.				
2.2.3.	"Category M3":	Vehicles used for the carriage of passengers, comprising more than eight nine seats in addition to the driver's seat or designed to carry standing passengers, and having a maximum mass exceeding 5 tonnes.				
2.2.4.	Vehicles of categories M2 and M3 belong to:					
2.2.4.1.	For vehicles having a capacity exceeding [23] occupants 22 passengers in addition to the driver, there are three classes of vehicles:					
2.2.4.1.1.	"Class I": Vehicles co	": Vehicles constructed with areas for standing passengers, to allow frequent passenger movement.				
2.2.4.1.2.	"Class II": Vehicles constructed principally for the carriage of seated passengers, and designed to allow the carriage of standing passengers in the gangway and/or in an area which does not exceed the space provided for two double seats.					
2.2.4.1.3.	"Class III": Vehicles co	Class III": Vehicles constructed exclusively for the carriage of seated passengers.				
2.2.4.1.4.	. A vehicle may be regarded as belonging in more than one class. In such a case it may be approved for each class to which it corresponds.					
2.2.4.2.	2.2.4.2. For vehicles having a capacity not exceeding [23] occupants 22 passengers in addition to the driver, there are two classes of vehicles:					
2.2.4.2.1.	"Class A": Vehicles de passengers	esigned to carry standing passengers; a vehicle of this class has seats and shall have provisions for standing s.				
2.2.4.2.2.	"Class B": Vehicles no	ot designed to carry standing passengers; a vehicle of this class has no provision for standing passengers.				

Source: OICA/CLEPA proposal GRVA-17-37

Additional task: New vehicle (sub)-categories





Categories according to Consolidated Resolution R.E.3

New categories:

New "Dual-mode" sub category:

- 2.x. Dual-mode vehicles with Automated Driving Systems
- 2.x.1. Definition.

Dual-mode vehicles are vehicles of category M or N which can be driven manually and which are equipped with an Automated Driving System allowing the vehicle to be driven in an automated mode not issuing a [system initiated deactivation to manual driving] requiring an interaction by a driver to take back manual control (e.g. a fallback user).

2.x.2 Categorization

Dual-mode vehicles are categorized into two categories, based on the maximum operational design speed of the Automated Driving System. In cases were the Automated Driving System consists of multiple features, e.g. low-speed and high-speed ADS features, the feature with the highest maximum design speed is defining the maximum design speed of the Automated Driving System and therefore considered for the dual-mode categorization.

- 2.x.2.1. Category D are dual mode vehicles having a maximum operational speed of the Automated Driving System exceeding [25] km/h.
- Category Z are dual mode vehicles having a maximum operational speed of the Automated Driving System not exceeding [25] km/h. 2.x.2.2.

2.x.3. Combined designation

Symbols M and N may be combined with symbol D or Z. For example, a vehicle of category M1 which is suited for dual-mode use having a maximum operational speed of the Automated Driving System exceeding [25] km/h may be designated as M1D.

Source: OICA/CLEPA proposal GRVA-17-37

Additional task: New vehicle (sub)-categories





Categories according to Consolidated Resolution R.E.3

New categories:

New "Dual-mode" sub category:

- Dual-mode vehicles with Automated Driving Systems 2.x.
- 2.x.1. Definition.

Dual-mode vehicles are vehicles of category M or N which can be driven manually and which are equipped with an Automated Driving System allowing the vehicle to be driven in an automated mode not issuing a [system initiated deactivation to manual driving] requiring an interaction by a driver to take back manual control (e.g. a fallback user).

2.x.2 Categorization

Dual-mode vehicles are categorized into two categories, based on the maximum operational design speed of the Automated Driving System. In cases were the Automated Driving System consists of multiple features, e.g. low-speed and high-speed ADS features, the feature with the highest maximum design speed is defining the maximum design speed of the Automated Driving System and therefore considered for the dual-mode categorization.

- Category D are dual mode vehicles having a maximum operational speed of the Automated Driving System exceeding [25] km/h. 2.x.2.1.
- 2.x.2.2. Category Z are dual mode vehicles having a maximum operational speed of the Automated Driving System not exceeding [25] km/h.

Combined designation 2.x.3.

Symbols M and N may be combined with symbol D or Z. For example, a vehicle of category M1 which is suited for dual-mode use having a maximum operational speed of the Automated Driving System exceeding [25] km/h may be designated as M1D.

Source: OICA/CLEPA proposal GRVA-17-37

e.a. Hub-2-Hub truck

e.g. AVP equipped vehicle

Additional task: New vehicle (sub)-categories





1-2Y

[25] km/h </= v </= [50] e.g. Urban shuttle

Vehicle categorization under S.R.1

New sub categories for Automated Vehicles (AV's)

Subcategory A "Driverless Vehicles with ADS" Designed primarily for Subcategories X & Y Designed primarily for Designed primarily for Subcategory D Designed primarily for "Low speed driverless AV's" "Dual Mode vehicles" the carriage of people the carriage of goods the carriage of people the carriage of goods With or w/o passengers Examples: Examples: 1-1A 1-1 1-2X Driver seat + max. 8 add. seats. seated only, max. 9 seating only seated passengers positions e.a. Robotaxi < [25] km/h e.g. Campus shuttle 1-2A

1-2A

More than 9 passengers

(standing and/or seated)

OICA/CI FPA proposal GRVA-17-37

Source:

Vehicles which can be driven manually under nominal conditions

1-2

Driver seat + more than 8 add. Seats.

seated and/or standing passengers

Additional task: New vehicle (sub)-categories





Vehicle categorization under R.E.3

New sub categories for Automated Vehicles (AV's)

Subcategory A .. Driverless Vehicles with ADS" Subcategories X & Y Designed primarily for "Low speed driverless AV's" the carriage of goods

Designed primarily for the carriage of people

Designed primarily for the carriage of goods

Subcateaory D "Dual Mode vehicles" Designed primarily for the carriage of people

Examples:

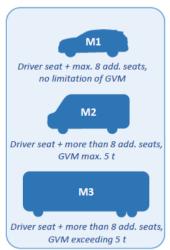
M2X

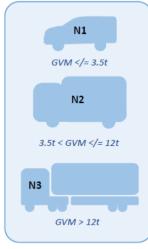
< [25] km/h

M2Y

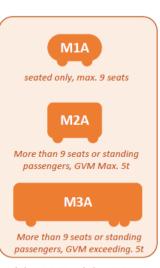
[25] km/h </= v </= [50] e.a. Urban shuttle

e.a. Campus shuttle

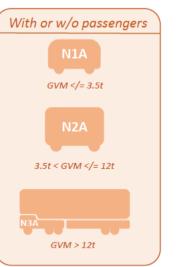


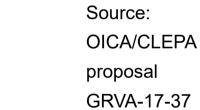










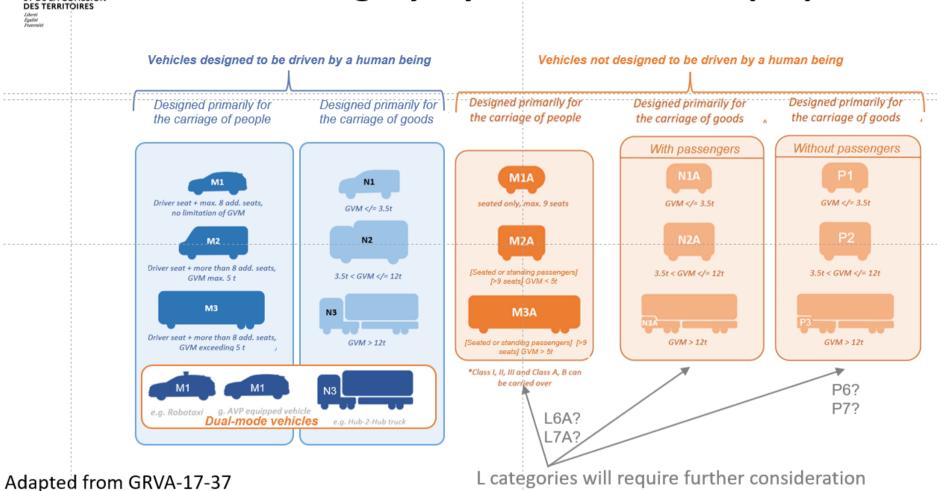


Vehicles which can be driven manually under nominal conditions

Additional task: New vehicle (sub)-categories

MINISTÈRE

MINISTÈRE : ÉCOLOGIQUE ET DE LA COHÉSION



Potential category layout for technical purposes

Quelle:

 French poposal FADS-J1-06 presented at the TF leader meeting of all GR TF's AVRS, Paris 16./17.10.2023. based on OICA/CLEPA proposal GRVA-17-37

Additional task: New vehicle (sub)-categories

Comments on OICA proposal

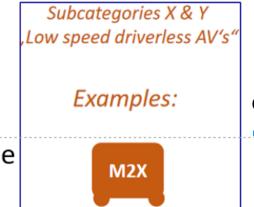
"Low-speed driverless AV's"

- Low maximum speed is not specific to AVs
- Regulations already handle low max speed in their scope

R13: "This Regulation does not cover vehicles with a design speed not exceeding 25 km/h"

 Shuttles with standing passengers and < 9 seats could be considered, but are not always AVs







< [25] km/h

Quelle:

French poposal
FADS-J1-06
presented at the TF
leader meeting of all
GR TF's AVRS, Paris
16./17.10.2023, based
on OICA/CLEPA
proposal GRVA-17-37

From GRVA-17-37



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