Proposal for 02 series of amendments to UN Regulation No. 160 (Event Data Recorder)

Submitted by the Working Party on General Safety *

Revision

The text reproduced below was adopted by the Working Party on General Safety (GRSG) at its 125th session (ECE/TRANS/WP.29/GRSG/104 para. 30). It is based on GRSG-125-02-Rev.2 as reproduced in annex V to the report. It is submitted to the World Forum for Harmonization of Vehicle Regulations (WP.29) and to the Administrative Committee (AC.1) for consideration at their November 2023 sessions.

* In accordance with the programme of work of the Inland Transport Committee for 2023 as outlined in proposed programme budget for 2023 (A/77/6 (Sect. 20), table 20.6), the World Forum will develop, harmonize and update UN Regulations in order to enhance the performance of vehicles. The present document is submitted in conformity with that mandate.
Paragraph 4.2., amend to read:

"4.2. An approval number shall be assigned to each approved type in accordance with Schedule 4 of the Agreement (E/ECE/TRANS/505/Rev.3)."

Insert new paragraph 6., to read:

"6. Verification Procedures

6.1. The accuracy of the measurement of longitudinal and lateral acceleration data element shall be verified using a component test fixture that subjects the EDR/airbag control module acceleration sensors to a sinusoidal acceleration motion in accordance with the following:

\[ a(t) = -40 \times \sin \left( \frac{\pi t}{20} \right) + /- 2g \]

6.1.1. The component test fixture shall be equipped with an acceleration sensor with a minimum range of + /- 500g and associated data acquisition system with a sampling frequency of 10kHz that is oriented to sense acceleration in the direction of the test fixture’s motion.

6.1.2. The air bag electronic control unit/EDR and applicable peripheral sensors, if needed to generate the air bag deployment signal, shall be mounted on the component test fixture as oriented in the vehicle. If the above does not generate a deployment signal, the manufacturer shall recommend the most appropriate way to generate the deployment signal.

6.1.3. The air bag deployment signal shall be recorded along with the component test fixture’s acceleration.

6.1.4. Following the activation of the component test fixture, the acceleration traces recorded by the component test fixture shall be passed through a 150 Hz two pole Butterworth filter. The equation for the 150 Hz Butterworth filter is shown below:

\[
\begin{align*}
    a_{\text{ref}_{150Hzfilt}}(n) &= 0.00208057 \times a_{\text{ref}_{\text{raw}}}(n) \\
    &+ 0.00416113 \times a_{\text{ref}_{\text{raw}}}(n-1) \\
    &+ 0.00208057 \times a_{\text{ref}_{\text{raw}}}(n-2) \\
    &+ 1.86689228 \times a_{\text{ref}_{150Hzfilt}}(n-1) \\
    &- 0.87521455 \times a_{\text{ref}_{150Hzfilt}}(n-2)
\end{align*}
\]

The filtered component test fixture acceleration traces shall be compared to the acceleration traces recorded in the EDR unit by aligning the traces using the air bag deployment signal time.

6.1.5. The EDR recorded acceleration trace shall be fully contained in a corridor that is +/- 10 per cent of the full-scale range of the accelerometer used by the controller containing the EDR applied to the component test fixture’s filtered acceleration trace. The comparison of acceleration sensor traces shall only be made on the axis the component test was conducted.

For example, if the accelerometer in the controller containing the EDR function has a +/- 100 g range, then +/- 10 g would be applied to the component test fixture’s filtered acceleration trace. The EDR recorded acceleration trace shall be fully contained within that corridor (see the figure).

Corridor +/- 10 Per Cent of the Full-Scale Range of the Accelerometer
6.1.6. The EDR acceleration trace in paragraph 6.1.5. can be time shifted up to +/- 2ms based on the inverse of the 500 Hz sample rate to further align the data. The minimum step of the time shift may be the inverse of the sample rate of the EDR.

6.1.7. The acceleration data elements satisfy the tolerance condition if the EDR recorded acceleration trace is fully contained within the corridor established in paragraph 6.1.5., with or without following the above time shift in paragraph 6.1.6.

6.1.8. If the recommended waveform cannot realize algorithm wakeup due to the reason of manufacturer’s algorithm strategy, the manufacture may select a waveform, or amplify the suggested waveform. The waveform used for the EDR acceleration data accuracy shall be provided for review, if it is different than the waveform defined in the verification process.”

Paragraphs 6. to 11.4., renumber as paragraphs 7. to 12.4

Paragraph 11.5.(former), renumber as paragraph 12.5., and amend to read:

“12.5. Notwithstanding paragraph 12.4., Contracting...”

Insert paragraphs 12.6. to 12.10., to read:

“12.6. As from the official date of entry into force of the 02 series of amendments, no Contracting Party applying this Regulation shall refuse to grant or refuse to accept type approvals under this Regulation as amended by the 02 series of amendments.

12.7. As from 1 September 2024, Contracting Parties applying this Regulation shall not be obliged to accept type approvals to the 01 series of amendments to this Regulation, first issued after 1 September 2024.

12.8. Until 1 September 2026, Contracting Parties applying this Regulation shall accept type approvals to the 01 series of amendments to this Regulation, first issued before 1 September 2024.

12.9. As from 1 September 2026, Contracting Parties applying this Regulation shall not be obliged to accept type approvals issued to the 01 series of amendments to this Regulation.

12.10. Notwithstanding paragraph 12.9., Contracting Parties applying this Regulation shall continue to accept type approvals issued according to the 01 series of amendments of this Regulation, for vehicles which are not affected by the changes introduced by the 02 Series of amendments.”
Paragraph 11.6. (former), renumber as paragraph 12.11.

Annex 3, amend to read:

"Annex 3

Arrangements of approval marks

(see paragraphs 4.4. to 4.4.2. of this Regulation)

The above approval mark affixed to a vehicle shows that the vehicle type with regard to its EDR concerned has been approved in Germany (E 1) pursuant to UN Regulation No. 160. The first two digits of the approval number (02) indicate that the approval was granted in accordance with the requirements of the 02 series of amendments to UN Regulation No. 160.

..."

Annex 4, Table 1, amend to read:

"...

<table>
<thead>
<tr>
<th>Lateral acceleration (post-crash)</th>
<th>If Recorded</th>
<th>0–250 ms or 0 to End of Event Time plus 30 ms, whichever is shorter.</th>
<th>500</th>
<th>-50 to +50g</th>
<th>+/- 10%(^10)</th>
<th>1 g</th>
<th>Planar Rollover(^11)</th>
</tr>
</thead>
</table>

<table>
<thead>
<tr>
<th>Longitudinal acceleration (post-crash)</th>
<th>If Recorded</th>
<th>0–250 ms or 0 to End of Event Time plus 30 ms, whichever is shorter.</th>
<th>500</th>
<th>-50 to +50g</th>
<th>+/- 10%(^10)</th>
<th>1 g</th>
<th>Planar</th>
</tr>
</thead>
</table>

..."

Footnotes 10 to 17 (former), renumber as Footnotes 12 to 19.

\(^{10}\) +/- 10 per cent of the full range of the accelerometer used in the Electronic Control Unit (ECU) containing the EDR function as specified in paragraph 6.1.5.

\(^{11}\) Format for lateral acceleration recorded in rollover is at the option of the manufacturer.