

Robust imputation procedures in the presence of influential units in surveys

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Influential units

- In practice, we often face the problem of influential values in the selected sample
- An influential unit is a **legitimate unit** of the finite population. It is **not a measurement error**:
 - ▶ Gross error;
 - ▶ Measurement errors are detected at the editing stage and are treated either manually or by some form of imputation.
- **Assumption**: Influential units are legitimate observations (not errors)
- Survey statistics are typically **sensitive to the presence of influential units**

Influential units

- Including or excluding an influential unit in the calculation of survey statistics can have a dramatic impact on their magnitude
 - Their presence in the sample tends to make **classical estimators very unstable**
 - **large variance**
- Common issue in business surveys that collect economic variables whose distributions are highly skewed
 - ▶ Influential units are often associated with very large values or very large errors
 - ▶ **Stratum jumpers**: may combine a very large value and a large sampling weight

Influential units

- In the presence of influential units, an imputed estimator of a population total:
 - ▶ is (approximately) unbiased provided that the imputation model is correctly specified
 - ▶ may have a very large variance
- Treatment of influential values: produces stable but biased estimators
→ trade-off between bias and variance
- Objective: reduce the influence of units that have a large influence
- Our hope: the mean square error of the robust version is smaller than that of the corresponding classical estimator
- How to impute/estimate in the presence of influential units?

The setup

- U : finite population of size N ;
- **Goal**: estimate a population total of a survey variable y :

$$t_y = \sum_{i \in U} y_i$$

- S : sample of size n selected according to a given sampling design $p(S)$;
- I_i : sample selection indicator such that $I_i = 1$ if $i \in S$, and $I_i = 0$, otherwise;
- **Design-unbiased (or p -unbiased) estimator of t_y :**

$$\hat{t}_{HT} = \sum_{i \in S} d_i y_i$$

- ▶ $d_i = 1/\pi_i$: design weight attached to unit i ;
- ▶ π_i : first-order inclusion probability attached to unit i

The setup

- The survey variable Y is prone to missing values.
- Let r_i be the response indicator such that

$$r_i = \begin{cases} 1, & \text{if } y_i \text{ is observed,} \\ 0, & \text{if } y_i \text{ is missing.} \end{cases}$$

- Set of respondents: $S_r = \{i \in S; r_i = 1\}$.
- Set of nonrespondents: $S_m = \{i \in S; r_i = 0\}$.
- Imputed estimator of t_y :

$$\hat{t}_I = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i y_i^*,$$

where y_i^* is the imputed value for the missing y_i .

Deterministic linear regression imputation

- \mathbf{x} : vector of fully observed variables
- **Imputation model**

$$y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \epsilon_i,$$

such that

$$\mathbb{E}(\epsilon_i \mid \mathbf{x}_i) = 0, \mathbb{E}(\epsilon_i \epsilon_j \mid \mathbf{x}_i, \mathbf{x}_j) = 0, i \neq j \text{ and } \mathbb{V}(\epsilon_i \mid \mathbf{x}_i) = \sigma^2 \phi_i$$

with $\phi_i > 0$ (known)

- Estimator of $\boldsymbol{\beta}$ based on the responding units:

$$\hat{\mathbf{B}}_{\text{WLS}} = \left(\sum_{i \in S_r} d_i \mathbf{x}_i \phi_i^{-1} \mathbf{x}_i^\top \right)^{-1} \sum_{i \in S_r} d_i \mathbf{x}_i \phi_i^{-1} y_i$$

- Imputed value: $y_i^* = \mathbf{x}_i^\top \hat{\mathbf{B}}_{\text{WLS}}$

Imputed estimator

- Estimator of t_y after deterministic linear regression imputation:

$$\hat{t}_{I,WLS} = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}_{WLS}$$

- If the first moment of the imputation model is correctly specified, we have

$$\mathbb{E}_m \mathbb{E}_p \mathbb{E}_q (\hat{t}_{I,WLS} - t_y) = 0.$$

- That is, the estimator $\hat{t}_{I,WLS}$ is *mpq*-unbiased for t_y .
- However, $\hat{t}_{I,WLS}$ may be inefficient in the presence of influential units.

Two methods commonly used in practice

- **Robust regression:** Replace the estimator \hat{B}_{WLS} by a **robust version** $\hat{B}_R(c)$; for instance an **M-estimator** based on the Huber function;
→ $\hat{B}_R(c)$ is solution of

$$\sum_{i \in S_r} \psi_c \left(\frac{y_i - \mathbf{x}_i^\top \boldsymbol{\beta}}{\sqrt{\phi_i} \hat{\sigma}} \right) \frac{\mathbf{x}_i}{\sqrt{\phi_i}} = 0,$$

where $\psi_c(\cdot)$ is the so-called Huber function and c is a tuning constant.

- Typically, the value is set to 1.345 (as in classical statistics)
- **Imputed value:** $y_i^* = \mathbf{x}_i^\top \hat{B}_R(1.345)$
- **Other ψ -functions:** Biweight, Andrew, etc.
- **Other estimators:** GM, MM, LTS estimators, etc.
- **Objective of robust regression :** describe the behavior of the inliers (the non-outliers)

Huber function

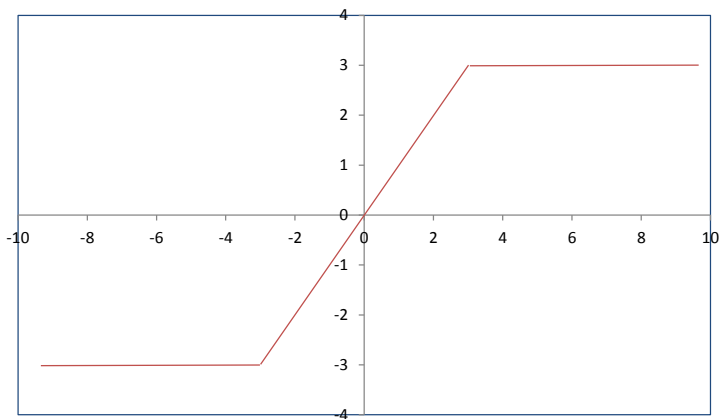


Figure 1: Huber function with $c = 3$

Two methods commonly used in practice

- **Excluding outliers:** Identify the influential units (usually by an outlier detection method), remove these units and obtain a predicted value obtained by fitting the customary linear regression model
- **Imputed value:** $y_i^* = \mathbf{x}_i^\top \hat{\mathbf{B}}_{\text{WLS}}^*$, where

$$\hat{\mathbf{B}}_{\text{WLS}}^* = \left(\sum_{i \in S_r} \omega_i \mathbf{x}_i \phi_i^{-1} \mathbf{x}_i^\top \right)^{-1} \sum_{i \in S_r} \omega_i \mathbf{x}_i \phi_i^{-1} y_i,$$

where $\omega_i = d_i$ if i is not discarded and $\omega_i = 0$ if i is discarded.

- **Underlying assumption:** the discarded respondent y -values are unique; i.e., they do not represent similar non-respondents \rightarrow **nonrepresentative respondents**

A simulation study

Are these methods satisfactory?

- We repeated 10, 000 iterations of the following process:
 - (1) A population U of size $N = 10,000$ was generated, with one survey variable Y and one covariate X using a mixture of normal distribution with a proportion of outliers equal to 5%;
 - (2) A sample S of size $n = 100; 200; 500$ was selected from U according to simple random sampling without replacement;
 - (3) Nonresponse to Y was generated according to a uniform nonresponse mechanism with $p_i = 50\%$ for all i ;
 - (4) Missing values were imputed using 3 imputation procedures.

A simulation study: Point estimators

We computed three types of imputed estimators:

- Non-robust estimator:

$$\hat{t}_{I,WLS} = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}_{WLS}$$

- Based on robust regression:

$$\hat{t}_I(c) = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}_R(c)$$

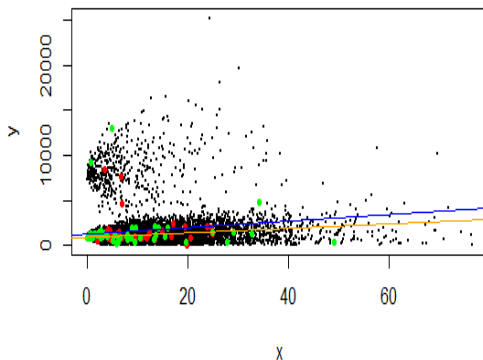
We used the Huber function with $c = 0.1; 1.345; 2.5$.

- Excluding the outliers:

$$\hat{t}_{I,WLS}^* = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}_{WLS}^*$$

We used the Cook distance with threshold $c = 4/(n - 3)$ and studentized residuals with $c = 2; 2.5; 3$.

A simulation study: Asymmetric outliers



$n = 100$

- Respondent
- Nonrespondent
- Nonsampled unit

- Least squares regression
- Robust regression

A simulation study: Results

- Monte carlo percent relative bias :

$$RB(\hat{t}_I) = \frac{\mathbb{E}_{MC}(\hat{t}_I - t_y)}{t_y} \times 100$$

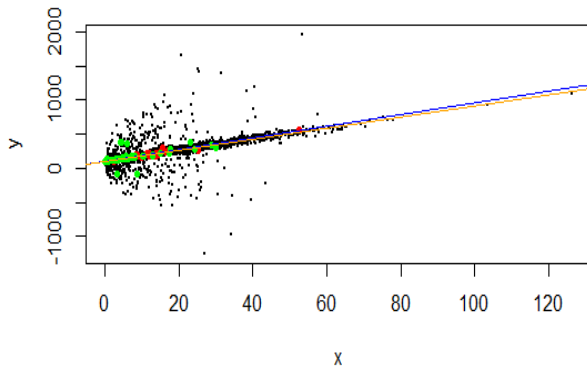
- Relative efficiency:

$$RE = 100 \times \frac{MSE_{MC}(\hat{t}_I)}{MSE_{MC}(\hat{t}_{I,WLS})}$$

	WLS	Robust regression			WLS (Exclude outliers)			
<i>n</i>		<i>c</i> = 0.1	<i>c</i> = 1.345	<i>c</i> = 2.5	Studentized <i>c</i> = 2	Studentized <i>c</i> = 2.5	Studentized <i>c</i> = 3	Cook distance
100	-0.0 (100)	-11.5 (78)	-10.7 (73)	-9.7 (70)	-9.3 (82)	-8.3 (84)	-7.5 (86)	-7.5 (87)
200	-0.2 (100)	-11.6 (128)	-10.8 (116)	-9.5 (102)	-9.1 (113)	-7.9 (111)	-6.9 (109)	-7.1 (110)
500	-0.2 (100)	-11.6 (260)	-10.8 (230)	-9.4 (190)	-8.5 (189)	-7.1 (166)	-6.0 (149)	-6.2 (156)

Table 1: Monte Carlo percent relative bias and Monte Carlo relative efficiency of several estimators

A simulation study: Symmetric outliers



$n=100$

- Respondent
- Nonrespondent
- Nonsampled unit

- Least squares regression
- Robust regression

A simulation study

- Monte carlo percent relative bias :

$$RB(\hat{t}_I) = \frac{\mathbb{E}_{MC}(\hat{t}_I - t_y)}{t_y} \times 100$$

- Relative efficiency:

$$RE = 100 \times \frac{MSE_{MC}(\hat{t}_I)}{MSE_{MC}(\hat{t}_{I,WLS})}$$

	WLS	Robust regression			WLS (Exclude outliers)			
n		$c = 0.1$	$c = 1.345$	$c = 2.5$	Studentized $c = 2$	Studentized $c = 2.5$	Studentized $c = 3$	Cook distance
100	-0.1 (100)	-0.1 (57)	-0.1 (57)	-0.1 (58)	-0.1 (57)	-0.1 (58)	-0.1 (60)	-0.1 (59)
200	-0.1 (100)	-0.0 (57)	-0.0 (57)	-0.0 (58)	-0.0 (57)	-0.0 (58)	-0.0 (59)	-0.0 (58)
500	-0.0 (100)	-0.0 (57)	-0.0 (57)	-0.0 (58)	-0.0 (57)	-0.0 (58)	-0.0 (59)	-0.0 (58)

Table 2: Monte Carlo percent relative bias and Monte Carlo relative efficiency of several estimators

Are these methods satisfactory?

- In the case of **symmetric outliers**, robust regression and weighted least squares regression after removing outliers, **behave very well in terms of bias and efficiency**;
- In the case of asymmetric outliers:
 - ▶ Robust regression and weighted least squares regression may work well in some scenarios but they **tend to breakdown as the sample size increases**
 - ▶ Why? Because the tuning constant c (e.g., $c = 1.345$) **was fixed** \longrightarrow **not adaptive**
- **c should be adaptive $\longrightarrow c$ increases as n increases**
- **At least two criteria:** Determine the value of c that minimizes
 - ▶ the estimated mean square error of the robust estimator: complex without simplifying assumptions
 - ▶ the maximum estimated conditional bias of the robust estimator; Beaumont et al. (2013); Chen et al. (2022)

Influence of a unit

- How measure the influence (or impact) of a unit?
- We measure the influence of $i \in S_r$ (respondent) using the concept of conditional bias:

$$B_i = \mathbb{E}_m \mathbb{E}_p \mathbb{E}_q (\hat{t}_{I,WLS} - t_y \mid Y_i = y_i, l_i = 1, r_i = 1) .$$

- After some algebra, we obtain

$$B_i \approx \sum_{j \in U} \left(\frac{\pi_{ij} - \pi_i \pi_j}{\pi_i \pi_j} \right) y_j + d_i \left(\sum_{\ell \in U} (1 - p_\ell) x_\ell^\top \right) \left(\sum_{\ell \in U} p_\ell x_\ell \phi_\ell^{-1} x_\ell^\top \right)^{-1} x_i \phi_i^{-1} (y_i - x_i^\top B)$$

- **First term on the right hand-side:** influence of unit i on the sampling error
- **Second term on the right hand-side:** influence of unit i on the nonresponse error
- B_i : unknown \longrightarrow It must be estimated

Influence of a unit

- **Special case:** simple random sampling without replacement and simple linear regression imputation (i.e., $x_i = (1, x_i)^\top$ and $\phi_i = 1$):

$$\hat{B}_i \approx \left(\frac{N}{n} - 1 \right) (y_i - \bar{y}_I) + \frac{1}{\hat{p}} \left\{ (1 - \hat{p}) + \frac{(x_i - \bar{x})(\bar{x} - \bar{x}_r)}{s_{xr}^2} \right\} (y_i - \hat{B}_{0,WLS} - \hat{B}_{1,WLS} x_i),$$

where

$$\bar{y}_I = \hat{t}_I / N, \quad \hat{p} = n_r / n, \quad s_{xr}^2 = (n_r - 1)^{-1} \sum_{i \in S_r} (x_i - \bar{x}_r)^2$$

- Responding unit i has a large influence if
 - ▶ The sampling fraction n/N is small;
 - ▶ Its y -value is far from the overall estimated mean \bar{y}_I ;
 - ▶ The response rate is low;
 - ▶ Its x -value is far from the overall estimated mean $\bar{x} \rightarrow$ **high leverage point**;
 - ▶ It has a **large vertical residual**, $y_i - \hat{B}_{0,WLS} - \hat{B}_{1,WLS} x_i$

First proposal

- Following Beaumont et al. (2013), we consider a robust version of

$$\hat{t}_{I,WLS} = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i x_i^\top \hat{B}_{WLS}$$

based on the concept of conditional bias:

$$\hat{t}_{I,CB}(c) = \hat{t}_{I,WLS} - \sum_{i \in S_r} \hat{B}_i + \sum_{i \in S_r} \psi_c \left\{ \hat{B}_i \right\} \equiv \hat{t}_{I,WLS} + \Delta(c),$$

where $\psi_c(\cdot)$ denotes the **Huber function**.

- Proposal:** select the value of c that minimizes

$$\max_{i \in S_r} \left| \hat{B}_i^R \right|,$$

where \hat{B}_i^R is the conditional bias (influence) of unit i on the robust estimator $\hat{t}_{I,CB}(c)$.

First proposal

- Resulting estimator:

$$\hat{t}_{I,CB}(c_{opt}) = \hat{t}_{I,WLS} - \frac{1}{2} \left[\min_{i \in S_r} \{ \hat{B}_i \} + \max_{i \in S_r} \{ \hat{B}_i \} \right]$$

- The value c_{opt} is obtained by solving

$$\Delta(c) = -\frac{1}{2} \left[\min_{i \in S_r} \{ \hat{B}_i \} + \max_{i \in S_r} \{ \hat{B}_i \} \right]$$

- There always exists a solution to the previous equation but the solution may not be unique; see Beaumont et al. (2013) and Favre Martinoz et al. (2015).
- c_{opt} increases as n increases $\longrightarrow \hat{t}_{I,CB}(c_{opt})$ is a consistent estimator of t_y ; see Chen et al. (2022).

Second proposal

- Idea: Propose an adaptative tuning constant c , c_{new} , and use robust regression (based on Huber function say) with this constant.
- Let $\hat{\mathbf{B}}_R(c_{\text{new}})$ be the solution of

$$\sum_{i \in S_r} \psi_{c_{\text{new}}} \left(\frac{y_i - \mathbf{x}_i^\top \boldsymbol{\beta}}{\hat{\sigma} \sqrt{\phi_i}} \right) \frac{\mathbf{x}_i}{\sqrt{\phi_i}} = 0,$$

where $\psi(\cdot)$ is the Huber function.

- Should we use the following estimator?

$$\hat{t}_{I,R}(c_{\text{new}}) = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}_R(c_{\text{new}})$$

- May not be a good idea because we are only "taking care" of the missing values. However, some respondents may also be influential

Second proposal

- If $\phi_i = \lambda^\top x_i$, then

$$\hat{t}_{l,WLS} = \sum_{i \in S} d_i x_i^\top \hat{B}_{WLS}$$

→ Projection form.

- Proposal:

$$\hat{t}_{l,R}(c_{\text{new}}) = \sum_{i \in S} d_i x_i^\top \hat{B}_R(c_{\text{new}}),$$

where

$$c_{\text{new}} = 1.345 \left\{ 1 + \frac{\left| \min_{i \in S_r} \{ \hat{B}_i^* \} + \max_{i \in S_r} \{ \hat{B}_i^* \} \right|}{2} \right\} + \frac{n}{N} \sqrt{n},$$

where \hat{B}_i^* denotes the standardized version of \hat{B}_i .

Second proposal

$$c_{\text{new}} = 1.345 \left\{ 1 + \frac{\left| \min_{i \in S_r} \{ \hat{B}_i^* \} + \max_{i \in S_r} \{ \hat{B}_i^* \} \right|}{2} \right\} + \frac{n}{N} \sqrt{n}$$

- If n/N small, the second term on the right hand-side is small \rightarrow we can omit it:
 - ▶ If the distribution has symmetric outliers, then c_{new} will be slightly larger than 1.345.
 - ▶ If the distribution has asymmetric outliers (say to the right), then c_{new} will be larger than 1.345.
- If n gets larger, then the second term on the right hand-side gets larger and $\hat{B}_R(c_{\text{new}})$ get closer and closer to \hat{B}_{WLS}

Simulation study: Set-up

10,000 iterations of the following process:

- (1) Generate a population of size $N = 1,000$;

Models used to generate the populations:

$$y_i \mid x_i \sim \mathcal{D}(\mu_i; \sigma^2 \phi_i),$$

- ▶ $\mu_i = \beta_0 + \beta_1 x_i$ and $\phi_i = x_i$; $x_i \sim \text{Gamma}(1, 10)$;
- ▶ \mathcal{D} : Normal, Lognormal, Pareto, Frechet, Weibull, Student, mixture of normals, mixture of lognormals.

- (2) From the population, select a sample of size $n = 50; 100; 200$ according to simple random sampling without replacement.
- (3) In each sample: generate nonresponse to the y -variable according to an uniform nonresponse mechanism with probability 50%.

Simulation study: Point estimators

- In each sample, we computed four estimators of t_Y :

- ▶ The non-robust estimator:

$$\hat{t}_{I,WLS} = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i x_i^\top \hat{B}_{WLS}$$

- ▶ The naive estimator:

$$\hat{t}_{I,R}(1.345) = \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i x_i^\top \hat{B}_R(1.345)$$

- ▶ The robust estimator based on the conditional bias:

$$\hat{t}_{I,CB}(c_{opt}) = \hat{t}_{I,WLS} - \frac{1}{2} \left[\min_{i \in S_r} \left\{ \hat{B}_i \right\} + \max_{i \in S_r} \left\{ \hat{B}_i \right\} \right]$$

- ▶ The robust estimator based on c_{new} :

$$\hat{t}_{I,R}(c_{new}) = \sum_{i \in S} d_i x_i^\top \hat{B}_R(c_{new})$$

Simulation study: Results

	Point estimator	Normal distribution	Lognormal distribution	Pareto distribution
$n = 50$	$\hat{t}_{I,WLS}$	-0.3 (100)	-0.1 (100)	-0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-0.4 (101)	-13.5 (73.6)	-8.3 (51)
	$\hat{t}_{I,CB}(c_{opt})$	-0.8 (100)	-7.2 (77)	-4.9 (56)
	$\hat{t}_{I,R}(c_{new})$	-0.2 (101)	-8.7 (73)	-7.0 (38)
$n = 100$	$\hat{t}_{I,WLS}$	0.0 (100)	-0.5 (100)	-0.0 (100)
	$\hat{t}_{I,R}(1.345)$	0.0 (102)	-14.6 (101)	-8.6 (59)
	$\hat{t}_{I,CB}(c_{opt})$	-0.3 (100)	-5.7 (84)	-3.8 (57)
	$\hat{t}_{I,R}(c_{new})$	-0.3 (100)	-6.1 (79)	-5.2 (39)
$n = 200$	$\hat{t}_{I,WLS}$	0.0 (100)	-0.2 (100)	-0.0 (100)
	$\hat{t}_{I,R}(1.345)$	0.0 (102)	-14.6 (151)	-8.6 (87)
	$\hat{t}_{I,CB}(c_{opt})$	-0.2 (100)	-3.6 (89)	-2.5 (64)
	$\hat{t}_{I,R}(c_{new})$	-0.2 (100)	-2.8 (89)	-3.1 (49)

Table 3: Monte Carlo percent relative bias and relative efficiency of several estimators

Simulation study: Results

	Point estimator	Frechet distribution	Weibull distribution	Student distribution
$n = 50$	$\hat{t}_{I,WLS}$	-0.1 (100)	0.0 (100)	0.4 (100)
	$\hat{t}_{I,R}(1.345)$	-9.2 (52)	-17.0 (87)	0.3 (73)
	$\hat{t}_{I,CB}(c_{opt})$	-5.4 (57)	-8.1 (86)	0.0 (81)
	$\hat{t}_{I,R}(c_{new})$	-7.6 (43)	-9.5 (86)	-0.0 (74)
$n = 100$	$\hat{t}_{I,WLS}$	0.0 (100)	-0.1 (100)	0.0 (100)
	$\hat{t}_{I,R}(1.345)$	-9.4 (67)	-17.9 (122)	0.1 (72)
	$\hat{t}_{I,CB}(c_{opt})$	-4.1 (65)	-5.7 (92)	-0.1 (84)
	$\hat{t}_{I,R}(c_{new})$	-5.6 (51)	-5.7 (92)	-0.1 (78)
$n = 200$	$\hat{t}_{I,WLS}$	0.0 (100)	-0.0 (100)	-0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-9.7 (93)	-18.5 (192)	0.0 (71)
	$\hat{t}_{I,CB}(c_{opt})$	-3.0 (69)	-3.6 (95)	-0.2 (87)
	$\hat{t}_{I,R}(c_{new})$	-3.4 (54)	-3.6 (95)	-0.0 (89)

Table 4: Monte Carlo percent relative bias and relative efficiency of several estimators

Simulation study: Results

	Point estimator	Mixture normal (0.01)	Mixture normal (0.03)	Mixture normal (0.05)
$n = 50$	$\hat{t}_{I,WLS}$	0.1 (100)	-0.1 (100)	-0.5 (100)
	$\hat{t}_{I,R}(1.345)$	-1.8 (78)	-5.2 (67)	-7.6 (65)
	$\hat{t}_{I,CB}(c_{opt})$	-1.8 (83)	-3.8 (79)	-4.5 (82)
	$\hat{t}_{I,R}(c_{new})$	-2.2 (76)	-6.0 (71)	-8.0 (79)
$n = 100$	$\hat{t}_{I,WLS}$	0.1 (100)	-0.1 (100)	0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-1.9 (78)	-5.3 (72)	-8.1 (78)
	$\hat{t}_{I,CB}(c_{opt})$	-1.5 (85)	-3.1 (86)	-3.8 (91)
	$\hat{t}_{I,R}(c_{new})$	-1.7 (79)	-4.6 (79)	-6.3 (89)
$n = 200$	$\hat{t}_{I,WLS}$	0.0 (100)	0.1 (100)	-0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-1.9 (82)	-5.2 (85)	-7.7 (101)
	$\hat{t}_{I,CB}(c_{opt})$	-1.2 (89)	-2.0 (93)	-2.1 (96)
	$\hat{t}_{I,R}(c_{new})$	-0.7 (90)	-2.0 (91)	-1.7 (96)

Table 5: Monte Carlo percent relative bias and relative efficiency of several estimators

Simulation study: Results

	Point estimator	Mixture lognormal (0.01)	Mixture lognormal (0.03)	Mixture lognormal (0.05)
$n = 50$	$\hat{t}_{I,WLS}$	0.1 (100)	0.0 (100)	-0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-1.6 (55)	-4.0 (48)	-6.1 (51)
	$\hat{t}_{I,CB}(c_{opt})$	-1.3 (63)	-2.8 (63)	-3.9 (69)
	$\hat{t}_{I,R}(c_{new})$	-2.0 (44)	-5.4 (47)	-7.9 (61)
$n = 100$	$\hat{t}_{I,WLS}$	0.0 (100)	0.0 (100)	0.1 (100)
	$\hat{t}_{I,R}(1.345)$	-1.8 (59)	-4.1 (58)	-5.0 (63)
	$\hat{t}_{I,CB}(c_{opt})$	-1.2 (66)	-2.4 (72)	-3.1 (80)
	$\hat{t}_{I,R}(c_{new})$	-1.8 (48)	-4.7 (57)	-6.8 (79)
$n = 200$	$\hat{t}_{I,WLS}$	0.0 (100)	-0.1 (100)	0.0 (100)
	$\hat{t}_{I,R}(1.345)$	-1.8 (66)	-4.0 (79)	-3.6 (81)
	$\hat{t}_{I,CB}(c_{opt})$	-0.9 (73)	-1.7 (83)	-2.1 (90)
	$\hat{t}_{I,R}(c_{new})$	-1.3 (58)	-3.3 (72)	-4.6 (96)

Table 6: Monte Carlo percent relative bias and relative efficiency of several estimators

Implementation via calibrated imputation

- Both robust estimators

$$\hat{t}_{I,CB}(c_{opt}) = \hat{t}_{I,WLS} - \frac{1}{2} \left[\min_{i \in S_r} \{ \hat{B}_i \} + \max_{i \in S_r} \{ \hat{B}_i \} \right]$$

and

$$\hat{t}_{I,R}(c_{new}) = \sum_{i \in S} d_i x_i^\top \hat{B}_R(c_{new})$$

need to be implemented.

- Estimation of totals: data users simply compute

$$\hat{t}_I = \sum_{i \in S} d_i \tilde{y}_i, \quad \tilde{y}_i = r_i y_i + (1 - r_i) y_i^*$$

- How to implement these estimator? → Calibrated imputation

Implementation via calibrated imputation

- Calibrated robust imputation: e.g., Ren and Chambers (2003), Beaumont (2005) and Chen et al. (2022)
- Illustration for $\hat{t}_{I,R}(c_{\text{new}})$
- **Initial imputed values:** $y_i^* = \mathbf{x}_i^\top \hat{\mathbf{B}}_{WLS}$
- We seek final imputed values, y_{iF}^* , $i \in S_m$, that minimize

$$\sum_{i \in S} G(y_{iF}^*/y_i^*),$$

subject to

$$\hat{t}_{I,F} \equiv \sum_{i \in S_r} d_i y_i + \sum_{i \in S_m} d_i y_{iF}^* = \sum_{i \in S} d_i \mathbf{x}_i^\top \hat{\mathbf{B}}(c_{\text{new}}),$$

where $G(\cdot)$ is a pseudo-distance function.

Estimation of the mean square error

- Estimator of the mean square error of $\hat{t}_{I,R}(c_{\text{new}})$:

$$\widehat{\text{MSE}} = \widehat{\mathbb{V}}(\hat{t}_{I,R}(c_{\text{new}})) + \max\left\{0, (\hat{t}_{I,R}(c_{\text{new}}) - \hat{t}_{I,WLS})^2 - \widehat{\mathbb{V}}(\hat{t}_{I,R}(c_{\text{new}}) - \hat{t}_{I,WLS})\right\}$$

- Obtaining the terms $\widehat{\mathbb{V}}(\hat{t}_{I,R}(c_{\text{new}}))$ and $\widehat{\mathbb{V}}(\hat{t}_{I,R}(c_{\text{new}}) - \hat{t}_{I,WLS})$ may be obtained using a pseudo-population bootstrap procedure, motivated by the reverse approach of Shao and Steel (1999) for variance estimation in the presence of imputed data.
- Future work:** Conduct a simulation study to assess the performance of $\widehat{\text{MSE}}$, in terms of bias.

THANK YOU.