Informal document **GRVA-14-18**14th GRVA session 26-30 September 2022
Provisional agenda item 6(a)

Report of the TF on ADAS for the 14th GRVA Session

Status after the 13th GRVA session

- Two online meetings (1 June, 30 August)
- Four online meetings of the Drafting Group
- Two proposals for UN R 79 are kept on hold
- One new proposal for UN R 79 had been considered by the TF
- Link to the TF documents: https://wiki.unece.org/display/trans/ADAS

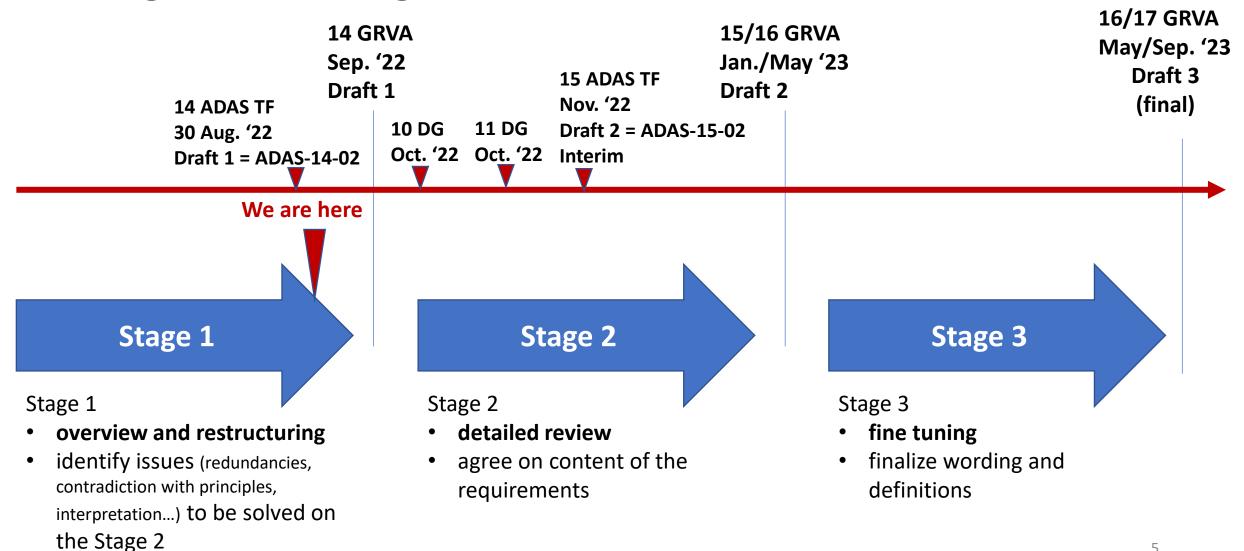
Outcome on the pending proposals for UN R 79

Document	System	Objective of the proposal	Status
GRVA/2021/09	ACSF C	Introduce a tolerance of 10% to the critical distance.	Pending a revised proposal. No change in the status. The request is to keep the working document in the GRVA agenda.
GRVA/2021/10	ACSF C	Extend allowed time to start a LCM to 7 s (or more).	Pending a revised proposal. No change in the status. The request is to keep the working document in the GRVA agenda.
GRVA-14-XX New proposal	ACSF C	Additional clarification regarding activation of ACSF C	The proposal had been considered by the TF and the comments had been provided to OICA+CLEPA.

Progress with drafting the DCAS UN Regulation

- The Small Drafting Group (SDG) was set up at the 11th ADAS TF session
 - The SDG participants: RUS, EC/JRC, NL, UK, AVERE, OICA, CLEPA, AAPC
- The SDG:
 - Developed and agreed DCAS key principles, which were further agreed by the ADAS TF at the 12th session
 - Developed the method of reviewing the Master Document (The latest version ADAS-13-02 was prepared by the TF Secretary and circulated within the SDG)
 - Started the consideration and revision and restructuring of the Master Document (starting point ADAS-13-02)
 - The resulting Master Document ADAS-14-02 was presented to the TF with the invitation to the stakeholders to provide comments and proposals

DCAS Master Document Review Process Stages & Timing



The Results of Restructuring (1)

MD ADAS-14-02

Cegula	ation	
		Introduction
	1.	Scope
	2.	Definitions
	3.	Application for approval
	4.	Approval
	5.	Specifications
	6.	Requirements for Specific DCAS Features
	7.	System Validation
	8.	Modification of vehicle type and extension of approval
	9.	Conformity of Production
	10.	Penalties for non-conformity of production
	11.	Production definitively discontinued
	12.	Names and addresses of Technical Services responsible for conducting approval tests Type Approval Authorities
Annexes		
	1	Communication
		Appendix 1 - Model assessment form for electronic systems
	2	Arrangements of approval marks
	3	Special requirements to be applied to the audit
		Appendix 1 - Model assessment form for DCAS
		Appendix X - System design to be assessed during the audit/assessment
		Appendix Y - Exemplary Classification
	4	Placeholder Annex 5
	5	Placeholder Annex 6

-	Constituent			
5. 5.1	Specifications Convert Requirements			
5.1.	General Requirements			
5.1.1.	General operational principles			
5.1.2.	DCAS interaction with other vehicle assistance systems			
5.1.3	Functional requirements			
5.1.3.1.	General OEDR requirements			
5.1.3.2.	System boundaries			
5.1.3.3.	Vehicle dynamic behaviour / system dynamic control assistance			
5.1.3.3.1.	Lane Keeping			
5.1.3.3.2.	Lane Change			
5.1.3.3.2.1.	General Requirements			
5.1.3.3.2.2.	Specific Requirements for driver initiated lane change assistance [Placeholder]			
5.1.3.3.4.	Deceleration			
5.1.4.	System safety response to detected failures			
5.1.5.	DCAS and driver interactions (two directions)			
5.1.5.1.	Driver operation of the system (what the driver does with the system)			
5.1.5.1.1.	DCAS modes of operation (off / stand-by / active)			
5.1.5.1.2.	System activation and deactivation			
5.1.5.1.2.x.	Preconditions for DCAS activation			
5.1.5.1.3.	System status information			
5.1.5.1.4.	System deactivation			
5.1.5.1.5.	Driver override			
5.1.5.2.	System assurance of driver engagement (what the system			
	does with the driver)			
5.1.5.2.1.	Driver monitoring strategy/mechanism			
5.1.5.2.1.1.	Monitoring Requirements			
5.1.5.2.1.2.	Criteria for proper driver engagement			
5.1.5.2.2.	Driver disengagement			
5.1.5.2.3.	Warning Cascade			
5.1.5.3.	Driver Information Material [education]/[instruction] with			
	regard to DCAS			

The Results of Restructuring (2)

MD ADAS-14-02

Regulation

-		
		Introduction
	1.	Scope
	2.	Definitions
	3.	Application for approval
	4.	Approval
	5.	Specifications
	6.	Requirements for Specific DCAS Features
	7.	System Validation
	8.	Modification of vehicle type and extension of approval
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Still under development

6.	Requirements for specific DCAS features
6.1.	Specific requirements for advanced driver initiated maneuvers
6.1.1.	Advanced driver initiated lane change
6.1.2.	Advanced assistance for other driver initiated maneuvers [Placeholder]
6.1.3.	[Low speed manoeuvring] [Placeholder]
6.2.	System initiated manoeuvers
6.2.1.	General requirements for system initated manoeuvres
6.2.1.1.	Functional requirements
6.2.1.2.	HMI
6.2.2.	Specific requirements for system initiated lane change
6.2.2.1.	Functional requirements
6.2.3.	Specific requirements for maneuvers to transition from one phase of lane keeping to another
6.2.3.1.	Functional requirements
6.2.3.2.	Special provisions for dedicated maneuvers
6.2.3.2.1	Special provisions when forming an access corridor for emergency and enforcement vehicles
6.3.	Specific requirements for hands-free driving [Placeholder] (VDA ongoing study)

Segregating Vehicle Control Assistance Systems between UN Regulation No.79 and DCAS UN Regulation (to be confirmed by the ADAS TF)

- UN Regulation No. 79 presently covers:
 - ACSF A, ACSF B1, ACSF C, CSF, ESF, RMF
- DCAS UN Regulation to cover:
 - Any other vehicle control assistance systems (see use cases in ADAS-08-04)
- DCAS is considered as a combination of different vehicle control assistance systems/functions, which could be type-approved at once
 - For each system/function included into the combination the manufacturer shall provide necessary documentation as it would require by the DCAS UN Regulation.
 - The combination may include systems presently covered by UN Regulation No. 79.
 - [It should be up to the manufacturer whether to apply for approval of these systems pursuant to UN Regulation No. 79 or pursuant to the new UN Regulation.]

Next steps

- Start of stage 2 with detailed review of the requirements
 - Section Modes of Operation
 - Section Driver Engagement Monitoring
 - Review of the existing requirements
 - Assessment of DCAS → elaborating on the annexes
- Introduction and definitions could be checked after finalizing the requirements in stage 3
- The DG meetings:
 - 1st week of October 2022 (TBC)
 - 3rd of 4th week of October (TBC)
- 15th ADAS TF session \rightarrow 1st or 2nd week of November 2022

Thank you for your attention!

Back-up

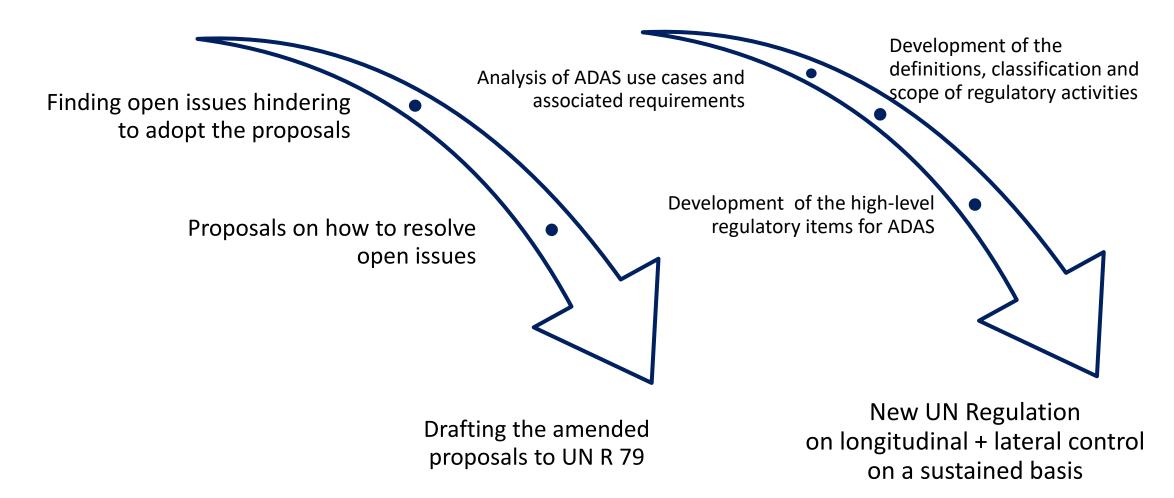
Background

- GRVA adopted at its 9th session in February 2021 the terms of reference for the Task Force on Advanced Driver Assistance Systems (ADAS).
- The Task Force (TF) focuses on Advanced Driver Assistance Systems (ADAS), and shall address the simplification of UN Regulation No. 79 and if needed, develop a new ADAS UN Regulation with a focus on ADAS systems up to of level 2 (as defined in ECE/TRANS/WP.29/1140).
- The TF on ADAS agreed to start developing a new UN Regulation

Two Parallel Workstreams of the TF

Working on the pending proposals for UN R 79

Development of the provisions for the new ADAS use cases



Agreed DCAS Key Principles

- 1. "Driver" refers to a human being driving a vehicle.
 - 1.1. A DCAS does not replace the driver (ADS); a DCAS assists the driver (ADAS).
 - 1.2. A DCAS does not change the driver's responsibilities for control of the vehicle.
- 2. A DCAS is a driver-operated vehicle system.
 - 2.1. A DCAS must prevent reasonably foreseeable risks of driver misuse or abuse.
 - 2.2. A DCAS must have means to evaluate continuous driver involvement in and supervision of the vehicle operation.
 - 2.3. A DCAS do not aim to permit driver activities other than driving in addition to those permitted for manual driving.
 - 2.4. A DCAS must provide sufficient information to enable the driver to supervise its motion-control assistance.
- 3. A DCAS assists the driver via sustained lateral and longitudinal motion-control support.
 - 3.1. The DCAS support must not adversely impact road safety.
 - 3.2. The DCAS support must not adversely impact driver control over the vehicle behavior.
- 4. The availability of a DCAS to the driver is constrained by defined system boundaries.
 - 4.1. The manufacturer must describe the system boundaries.

Procedure of SDG for the review (Stage 1)

Guiding questions:

- Does each requirement comply with key principles?
- Is each requirement applicable to all types of DCAS?
- Does it need to be moved in another place?
- Is side comment/discussion point relevant for this headline/sub-headline?
- Should additional paragraph(s) be introduced to address such side comment/discussion point?

Derived tasks

- Check if the existing requirements are in line with the principles and in the right place
- Add missing requirements, where necessary
- Clustering of the several DCAS features (what is specific, what in common?)
- Establishment of a new structure to address the clustering approach