

Disclosure Metrics Born From Statistical Evaluations of Data Utility

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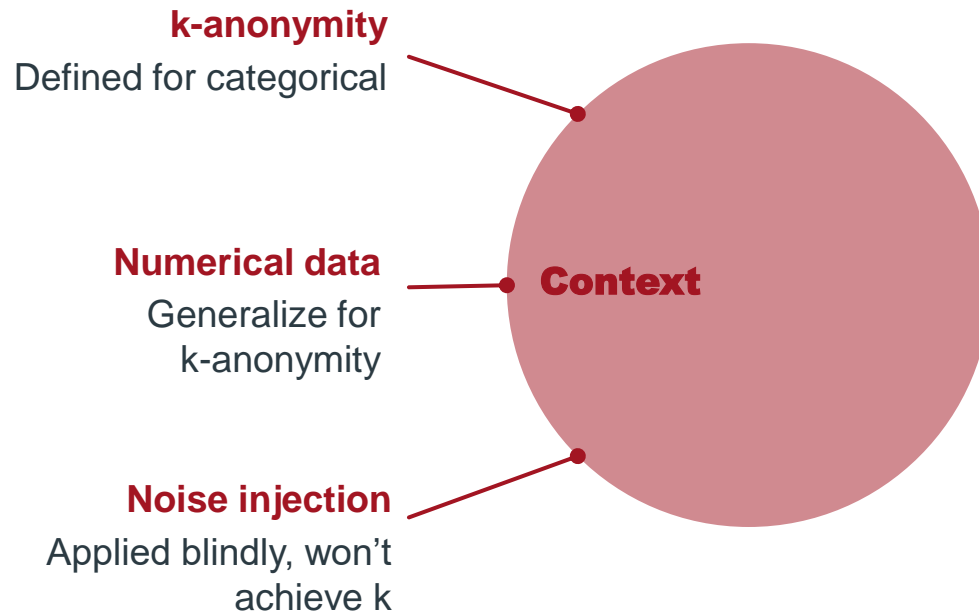
Agenda

- Background
- Privacy Models
- Empirical Results
- Ongoing Research

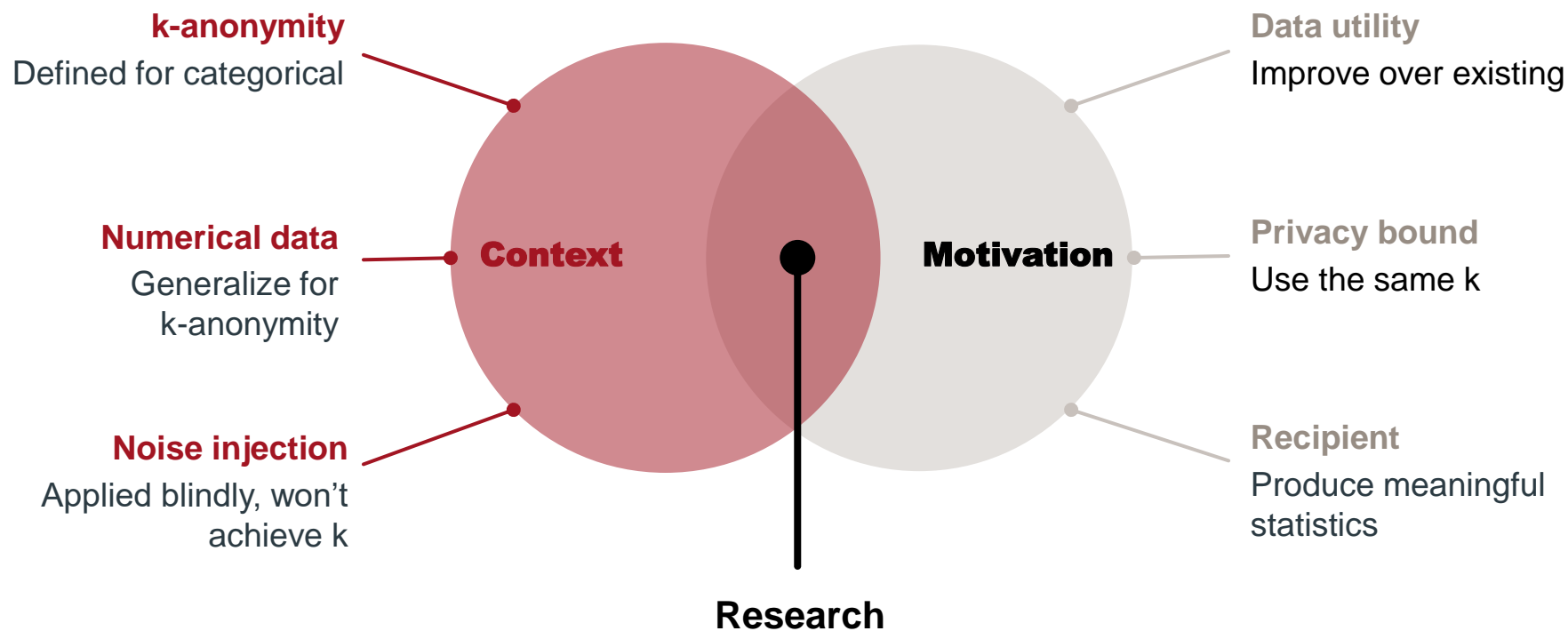
Context and Motivation

BACKGROUND

Context



Context and Motivation



Theoretical

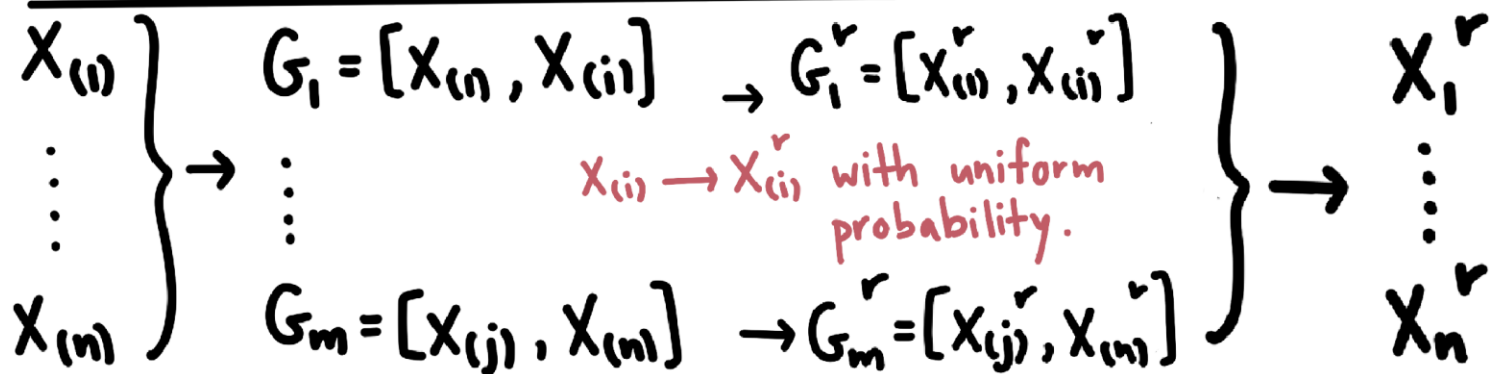
PRIVACY MODELS

Categorical Data

k-PRAM

Input: $\underline{X} = (X_1, \dots, X_n)$

Output: $\underline{X}^r = (X_1^r, \dots, X_n^r)$



Numerical Data

k-Noise

Input: $\underline{X} = (X_1, \dots, X_n)$

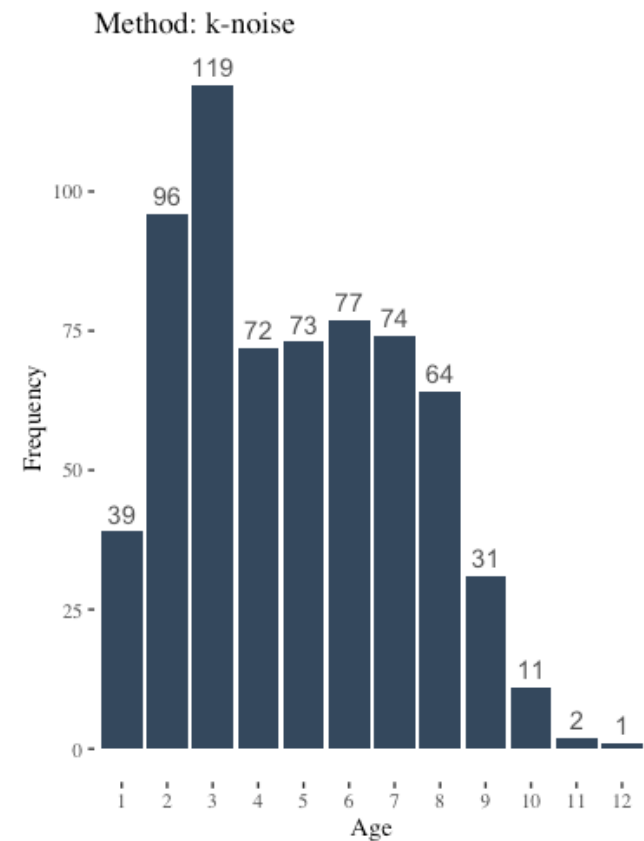
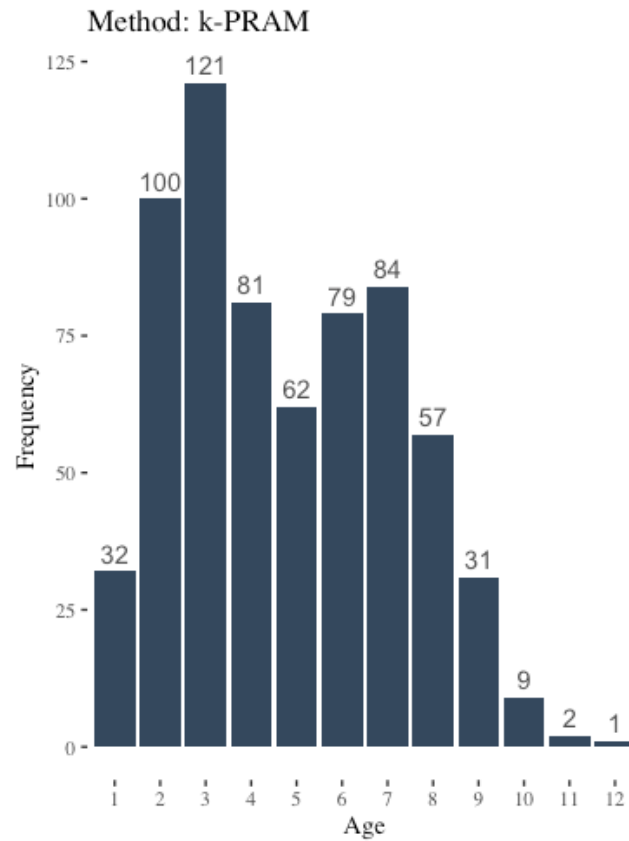
Output: $\underline{X}^r = (X_1^r, \dots, X_n^r)$

$$\begin{array}{ccccc}
 X_1 & & X_1 + \text{Uni}(-a, a) & & X_1^r \\
 \vdots & \longrightarrow & \vdots & \longrightarrow & \vdots \\
 X_n & & X_n + \text{Uni}(-a, a) & & X_n^r
 \end{array}$$

Experiments

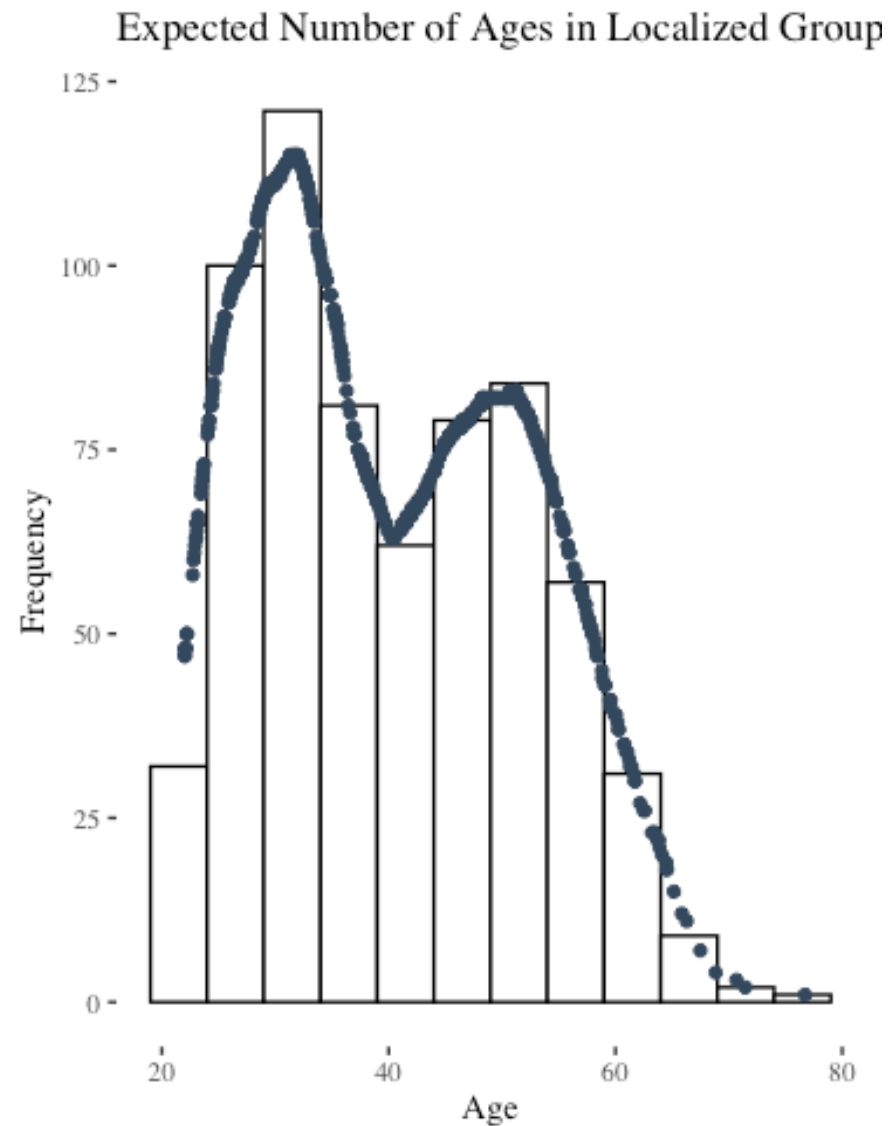
EMPIRICAL RESULTS

Baseline Level of Privacy



Baseline Level of Privacy

Expected number or records within a neighbourhood of $[-2.5, 2.5]$ years of each randomized record in X .



Data Utility Measures

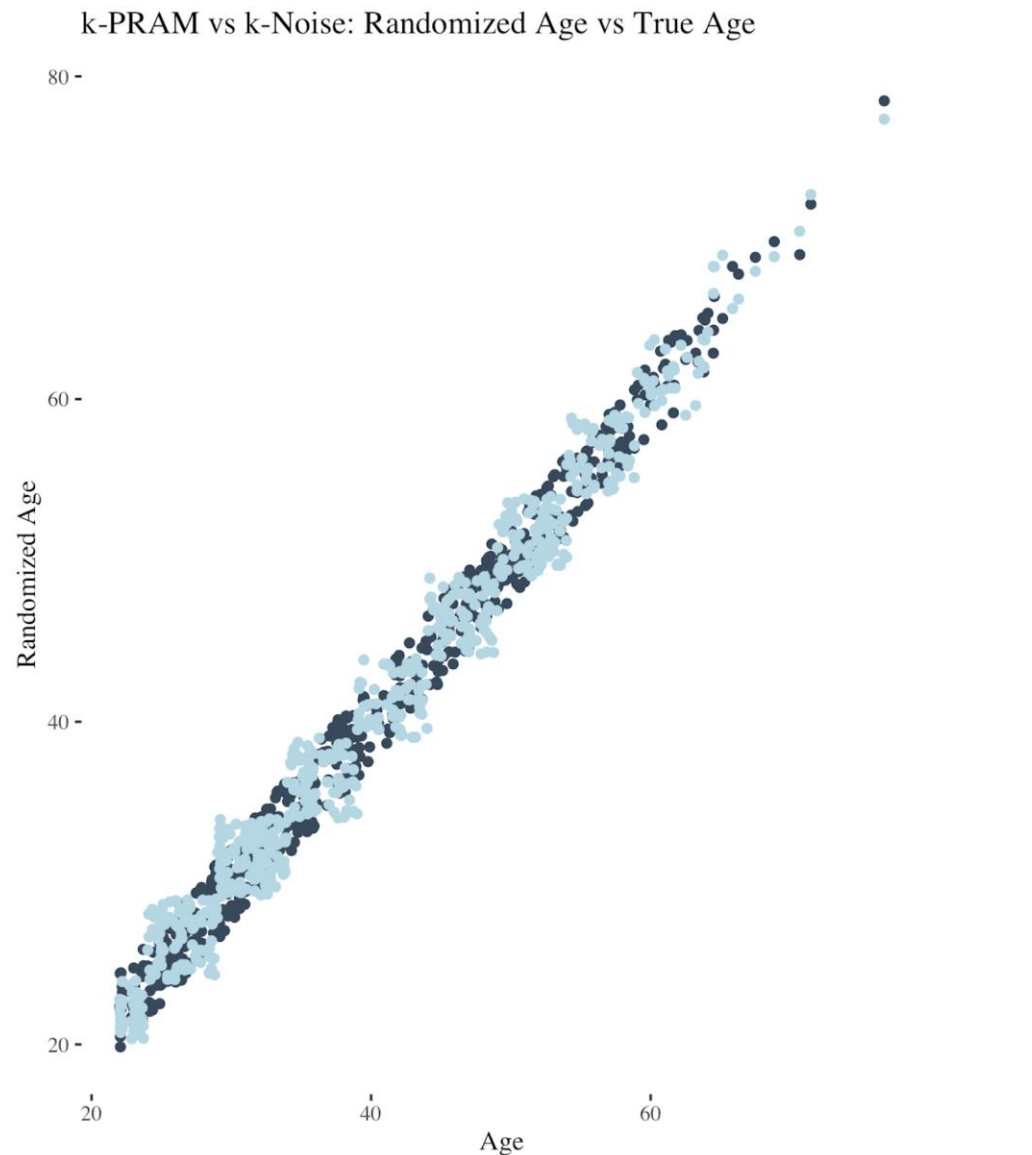
Summary of Utility Estimators

Method	Bias	Mse	Rmse
k-PRAM	0.076918689	4.368601	2.090120
k-Noise	-0.008230827	2.184711	1.478077

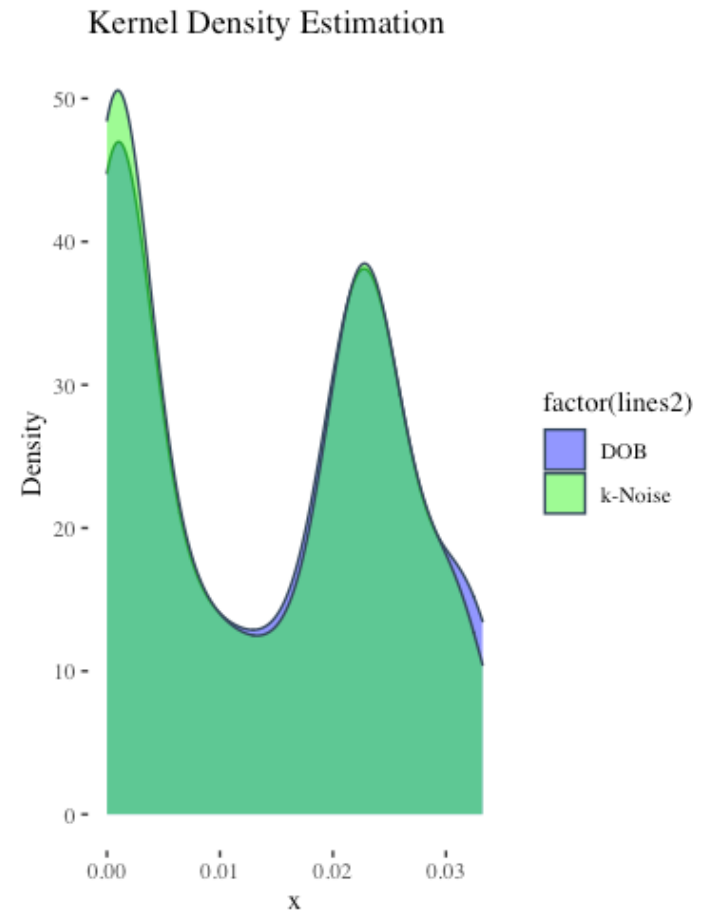
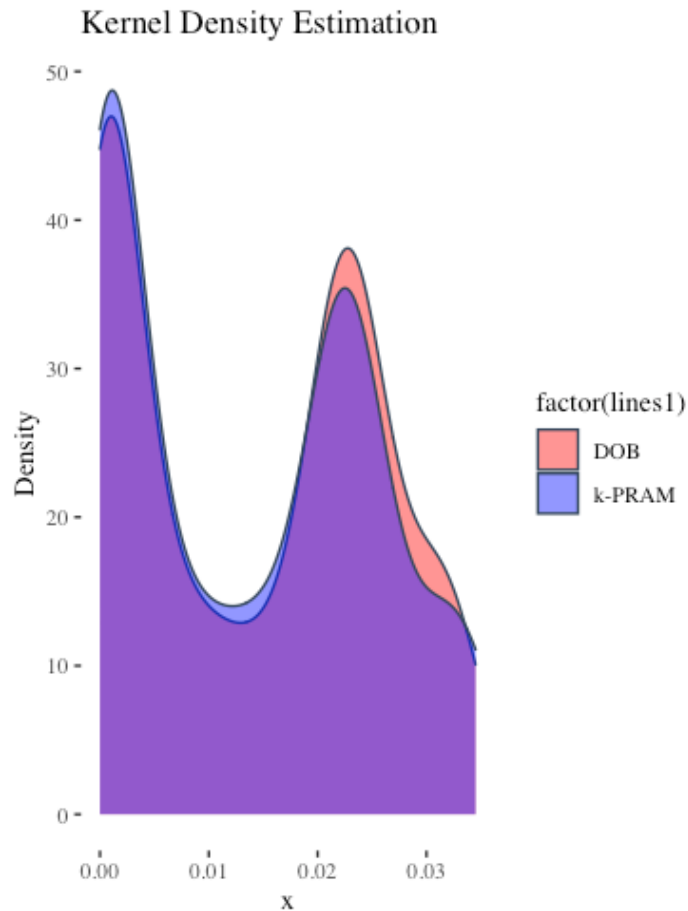
Data Utility Visual

The clustered scatter plot represents k-PRAM randomized individuals.

The bias calculated is visibly noticeable when comparing the two methods against the true value.



Data Utility Densities



Ongoing research

Multidimensional

Extend to handle correlations, sparsity, etc.

Distributions

Impact on data utility from different noise profiles

Adaptive

Localized noise injection based on empirical distribution

