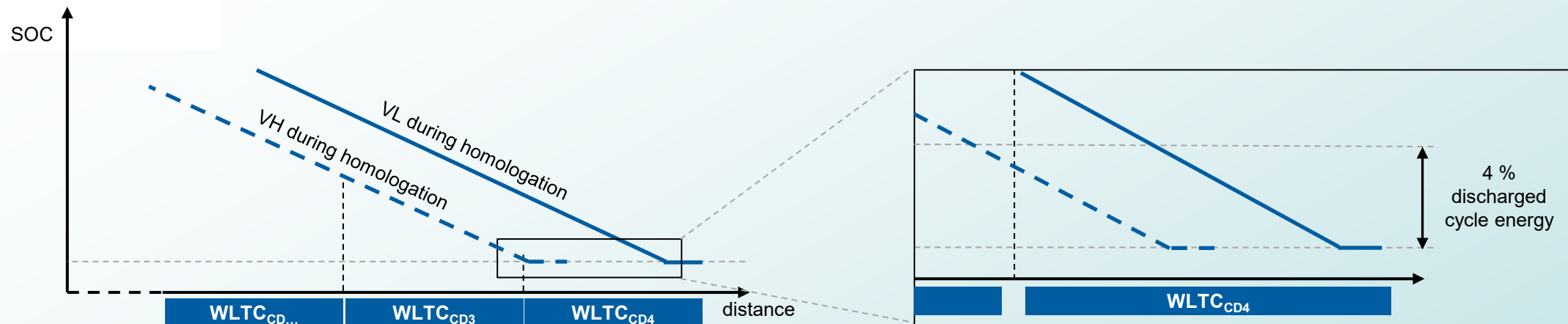




## EAER calculation VH and VL



	<u>Vehicle L</u>	<u>Vehicle H</u>
RCDC-nr.	4 (→ WLTC <sub>CD4</sub> is transition cycle)	3 (→ WLTC <sub>CD3</sub> is transition cycle)

### Current situation:

- For several calculation, the approach to use the number of CD cycles from vehicles L is already implemented as e.g. for  $EC_{AC,CD}$  (Annex B8, §4.3.1.)
- The implementation of this approach has been missed to be integrated for EAER (see next slide)
- Interpolation method working for the  $R_{CDC}$  difference of 1 cycle (between VH and VL) but manufacturer need to add a safety margin that is not caused by physical energy but by the calculation method (lessons learned)

# Overview of values\* where “VL approach” is applied

\*note: AER not in the tables as triggered by engine start

Except of  $FE_{CD}$  and EAER based values, all interpolated CD or weighted values apply the VL approach:

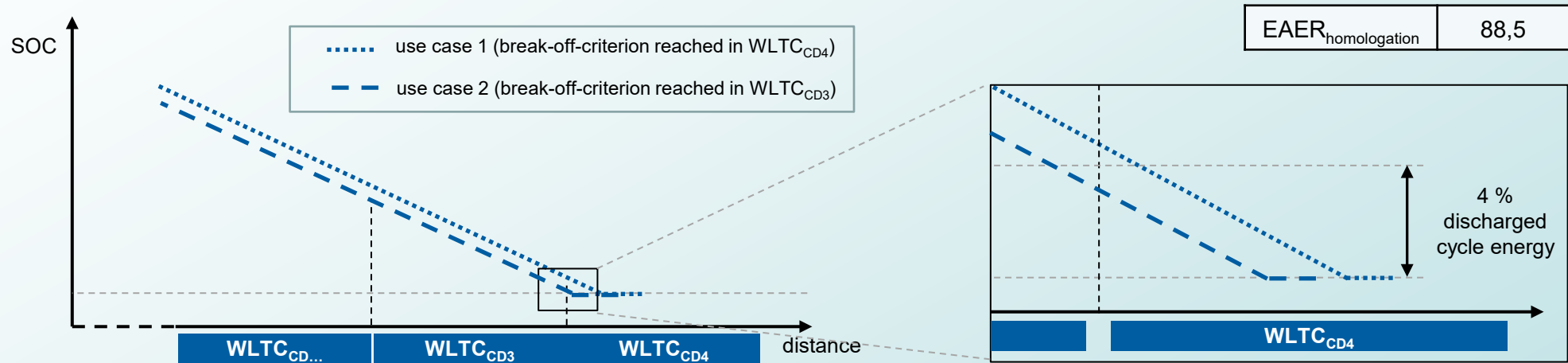
Parameter	Application of VL approach	Interpolation method
$M_{CO_2,CD}$ (both levels)	Yes	Yes
$M_{CO_2,weighted}$ (Level 1A)	Yes	Yes
$FC_{CD}$ (Level 1A)	Yes	Yes
$FE_{CD}$ (Level 1B)	No	Yes
$FC_{weighted}$ (Level 1A)	Yes	Yes
$EC_{AC,CD}$ (Level 1A)	Yes	Yes
$EC_{AC,weighted}$ (Level 1A)	Yes	Yes
EC (both levels) → (result of $E_{AC}$ divided by EAER)	No	Yes
$EC_p$ (both levels) → (result of $E_{AC}$ divided by $EAER_p$ )	No	Yes
EAER (both levels)	No	Yes
$EAER_p$ (both levels)	No	Yes

Only values, which are not using the interpolation method, are not applying the VL approach:

Parameter	Application of VL approach	Interpolation approach
$PN_{weighted}$ (both levels)	No	No
$PM_{weighted}$ (both levels)	No	No
$R_{CDA}$ (both levels)	No	No

Break-off criterion for the charge-depleting test (less than 4% of cycle energy from REESSs) influences  $R_{CDC}$

→ resulting EAER different → resulting SOCR indicator different → **Will lead to problems in context of EVE-GTR**



$$M_{CO2,CD,avg} = \frac{\sum_{j=1}^k (M_{CO2,CD,j} \times d_j)}{d_j}$$

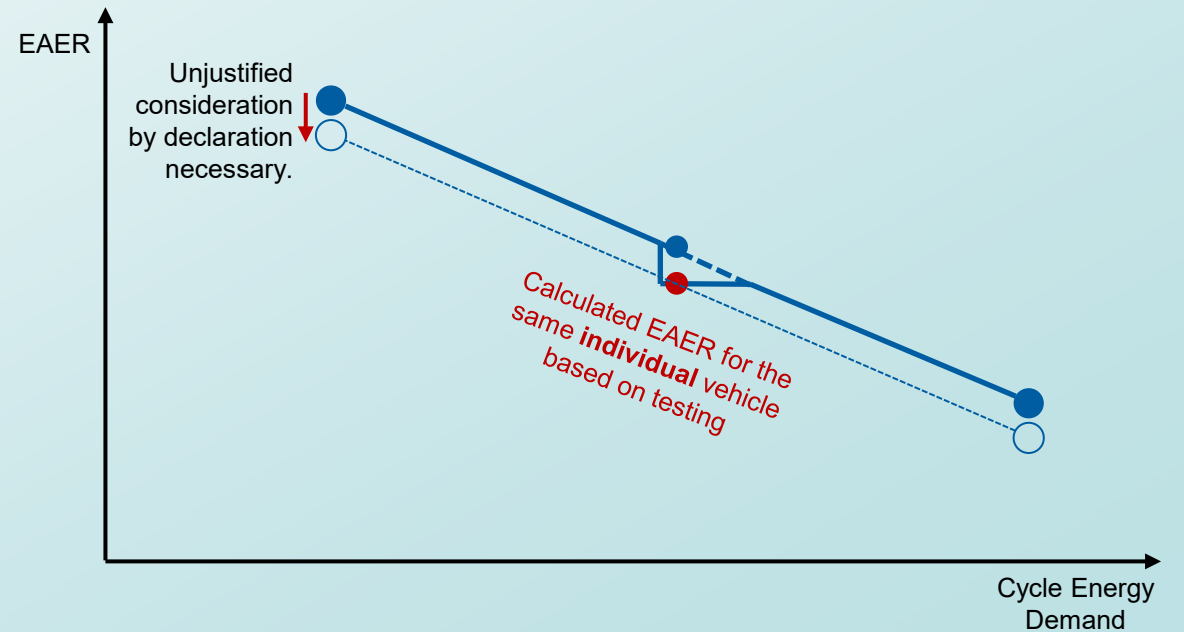
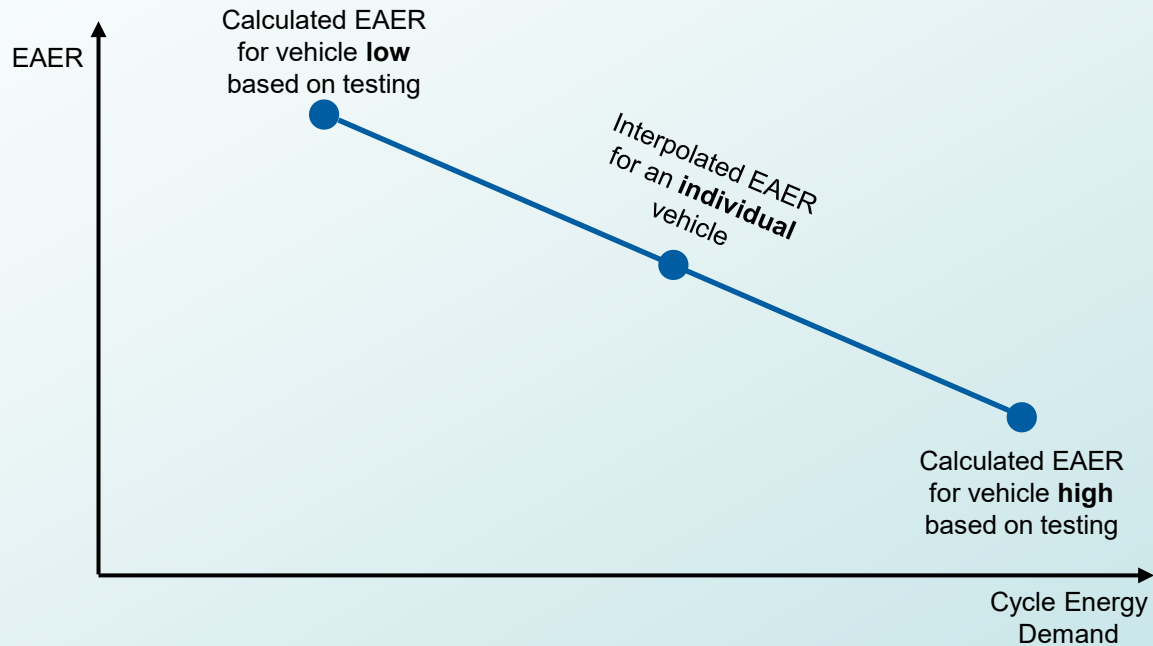
$$EAER_{measured} = \left( \frac{M_{CO2,CS} - M_{CO2,CD,avg}}{M_{CO2,CS}} \right) \times R_{cdc}$$

	<b>Use case 1: more than 4 % cycle energy discharged in WLTC<sub>CD,4</sub></b>	<b>Use case 2: less than 4% cycle energy discharged in WLTC<sub>CD,4</sub></b>
CO2_CD1	0	0
CO2_CD2	0	0
CO2_CD3	0	0
CO2_CD4	96	96
CO2_CS	100	100
RCDC-nr.	4 (→ WLTC <sub>CD4</sub> is transition cycle)	3 (→ WLTC <sub>CD3</sub> is transition cycle)
RCDC	93,2	69,9
EAER <sub>ISC</sub>	70,832	69,9
SOCR (EVE-GTR)	80	78,94736842

# Impacts of different $R_{CDC}$ on EAER

The interpolation approach assumes an linear character between low and high what is correct from a physical perspective, but...

... if an individual vehicle tested e.g. for ISC without keeping the  $R_{CDC}$  constant, there is a **non-physical-based** difference between the interpolated EAER and the calculated EAER based on a test. The only solution to cover this is to consider it with the declaration but the manufacturer should not be forced to cover methodical weak points.



## Action item ISC:

In context of an individual vehicle @ ISC (e.g. EVE-GTR) it is necessary to refer to the  $R_{CDC}$ -value determined during type approval.

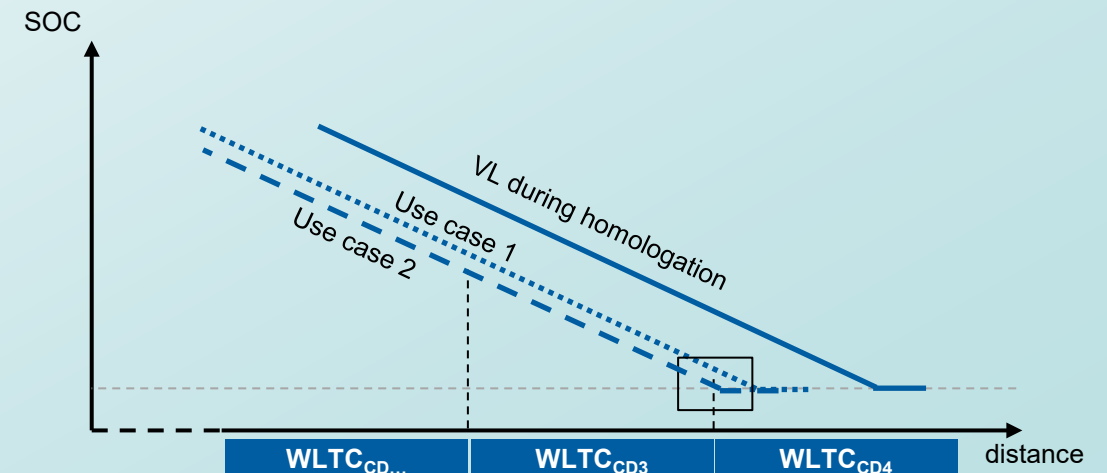
→ This eliminates the impact of the break-off-criterion on  $R_{CDC}$  and therefore on EAER for ISC-testing.

## Action item homologation:

→ In case of different  $R_{CDC}$ -values at homologation for VH and VL, some individual vehicles close to the break-off criterion (4% threshold) would lose EAER caused by the calculation method

→ Way forward to resolve this problem is just one  $R_{CDC}$ -value for the purpose of EAER calculation within one IP-family →  $R_{CDC}$  of vehicle L

	Homologation	Use case 1 ..... (dotted)	Use case 2 - - - (dashed)
Use case	VL @Type Approval (TA)	Vehicles with the same $R_{CDC}$ -value than VL@TA (e.g.: VH@TA or any individual vehicle in IPF)	Vehicles with different $R_{CDC}$ -value than VL@TA (e.g.: VH@TA or any individual vehicle in IPF or vehicles during ISC)
$R_{CDC}$ -value	4 x WLTC (WLTC <sub>CD4</sub> is transition cycle)	4 x WLTC (WLTC <sub>CD4</sub> is transition cycle)	3 x WLTC (WLTC <sub>CD3</sub> is transition cycle)
Action	No amendment required as this is reference.	No amendment required as $R_{CDC}$ identical to reference.	Amendment required as $R_{CDC}$ different to reference.



The following paragraphs in UN-R-154 would need to be amended:

- Annex B8, Paragraph 4.4.3. (Charge-depleting cycle range **for OVC-HEVs**) → **Bold** text to be added

The charge-depleting cycle range RCDC shall be determined from the charge-depleting Type 1 test described in paragraph 3.2.4.3. of this annex as part of the Option 1 test sequence and is referenced in paragraph 3.2.6.1. of this annex as part of the Option 3 test sequence. The RCDC is the distance driven from the beginning of the charge-depleting Type 1 test to the end of the transition cycle according to paragraph 3.2.4.4. of this annex.

**In the case that the interpolation method is applied, the transition cycle of vehicle L  $n_{veh\_L}$  shall be used for the RCDC determination. If the transition cycle number driven by vehicle H,  $n_{vehH}$ , and, if applicable, by an individual vehicle within the vehicle interpolation family  $n_{vehind}$  is lower than the transition cycle number driven by vehicle L,  $n_{veh\_L}$ , the confirmation cycle of vehicle H and, if applicable, an individual vehicle shall be used as the end of the transition cycle.**

- Amend UN R 154, Annex B8, §4.4.4.1. Determination of cycle-specific equivalent all-electric range
- Amend UN R 154, Annex B8, §4.4.6.1. Determination of cycle-specific equivalent all-electric range

→ Bold text to be added at the end of both paragraphs:

(...)

**In the case that the interpolation method is applied, k shall be the number of phases driven up to the end of the transition cycle of vehicle L  $n_{veh\_L}$ . If the transition cycle number driven by vehicle H,  $n_{vehH}$ , and, if applicable, by an individual vehicle within the vehicle interpolation family  $n_{vehind}$  is lower than the transition cycle number driven by vehicle L,  $n_{veh\_L}$ , the confirmation cycle of vehicle H and, if applicable, an individual vehicle shall be included in the calculation.**