

RESEARCH PROGRAM ON AN EMISSIONS TEST PROCEDURE FOR HEAVY DUTY HYBRIDS (HDH)

Development of Emissions and CO₂ Test Procedure for
Heavy Duty Hybrid Vehicles

WP3: Non-electric HDHs

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Summary

- WT 3-1:
 - Non-electric hybrid powertrain topologies (concepts) fits well into the same categories as for electric hybrid powertrains
 - ➔ HILS should be possible for non-electric HDHs

- WT 3-2:
 - Mathematical models for:
 - Flywheel
 - Accumulator
 - Pump/Motor
 - CVT
 - ➔ Similar model structures as proposed in Kokujikan No. 281

Summary

- WT 3-3:
 - Parameters specified for:
 - Flywheel
 - Accumulator  Working on getting relevant data
 - Pump/Motor
 - CVT
- WT 3-4:
 - I/O:s identified  Needs standardization
- Work done according to time plan

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WT 3-1: Technology overview and selection of scope

- Detailed analysis on what non-electric hybrid systems/components to be included in the HILS method. **Review of non-electric hybrid topologies** proposed in the literature, by OEMs and others. **Review of non-electric components**, such as flywheels, accumulators etc, used in non-electric powertrains proposed in the literature, by OEM and others. Together with OEMs and other partners decide which topologies that should be covered. Meetings with OEMs, will be co-planned with TU Graz and TU Wien in relation to WP 1-4 (TU Graz and TU Wien offer).
- The preliminary **result** is a **list of non-electric powertrain topologies** and a **list of components** that needs to be modeled.

Results

- Non-electric hybrid powertrain topologies (concepts) fits well into the same categories as for electric hybrid powertrains
- Non-electric hybrid powertrains can be divided into:
 - Series powertrain topologies
 - Parallel powertrain topologies
 - Split powertrain topologies

Interesting non-electric powertrain concepts:

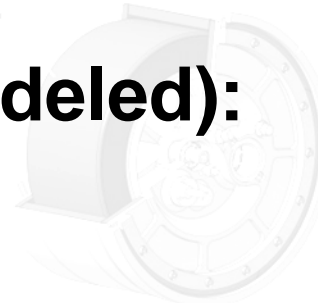
- CVT and flywheel
- Motor/generator and flywheel
- Hydraulic or (pneumatic) pump/motor and accumulator

Results

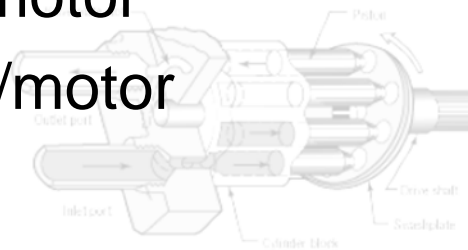
Component list (to be modeled):

- Energy storages:
 - Flywheel
 - Hydraulic accumulators
 - Pneumatic accumulators
- Energy converters
 - CVT (transmission)
 - Hydraulic pump/motor
 - Pneumatic pump/motor

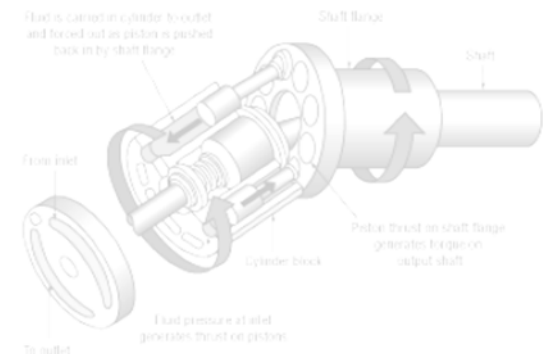
Flywheel in vacuum



Flywheel containment



(a) Swash-plate type, inline axial-piston type



(b) Bent-axis type, axial-piston type

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WT 3-2: Development of HIL elements for non-electrical hybrid systems/components

- Based on the list of topologies and components in WP 3-1, develop simple, representative **mathematical models** of the different powertrain components, such as actuators and energy buffers. The models will be implemented in a simulation software. All models will be documented.
- The result is a set of **simulation models of non-electric powertrain components**, which are suitable to use in a HILS setup.

Components

- Energy storages:
 - Flywheel
 - Hydraulic accumulators
 - Pneumatic accumulators
- Energy converters
 - CVT (transmission)
 - Hydraulic pump/motor
 - Pneumatic pump/motor

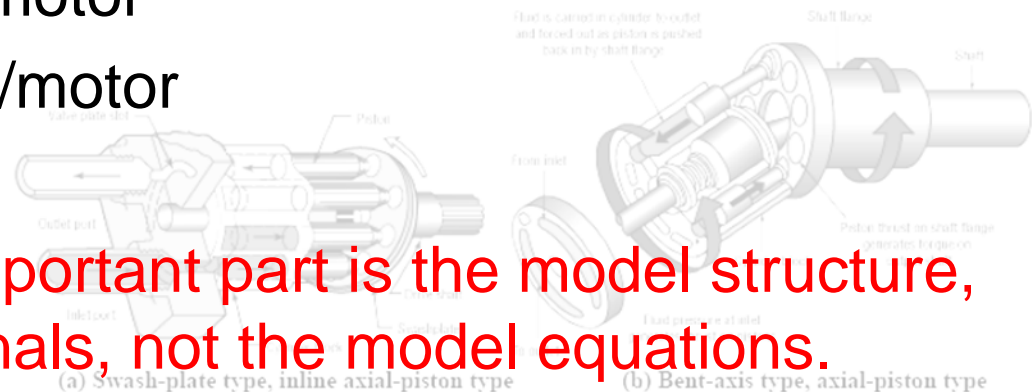
Flywheel in vacuum



Flywheel containment

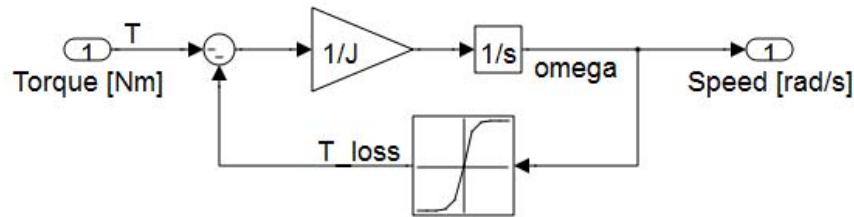


- Notice: The most important part is the model structure, the input-output signals, not the model equations.

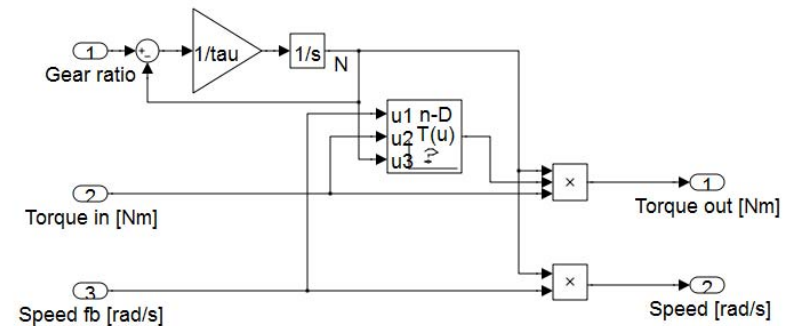


Component modeling

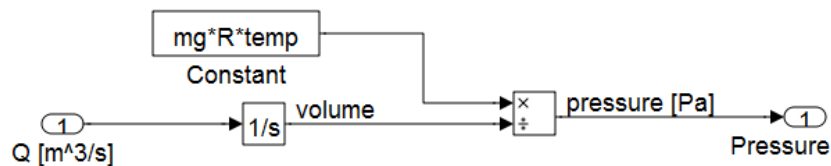
Flywheel



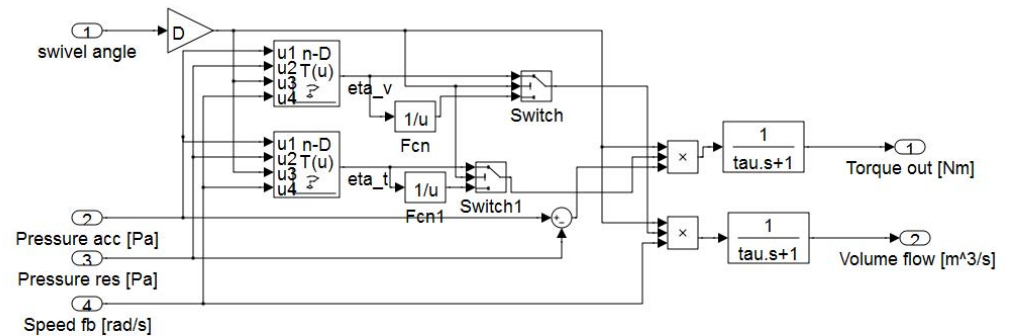
CVT



Accumulator



Hydraulic motor/pump



Results

- Mathematical models for
 - Flywheel
 - Accumulator
 - Pump/Motor
 - CVT
- MATLAB/Simulink implementation

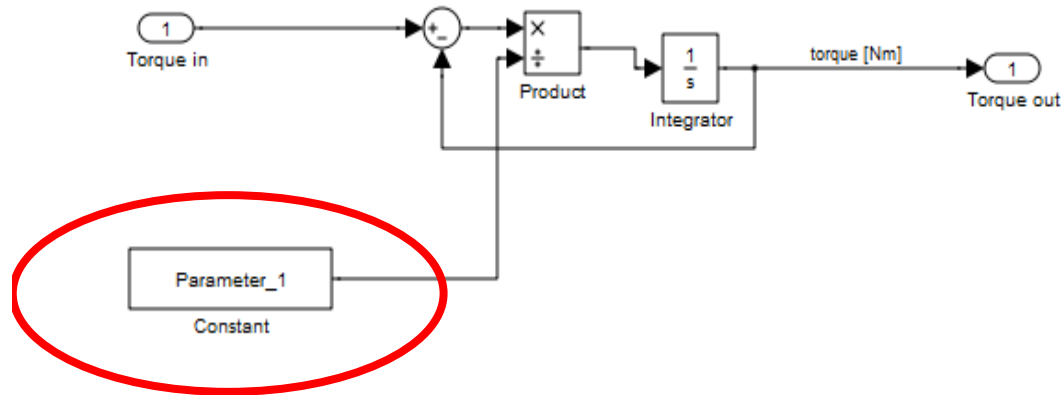
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WP 3-3: Test methods for input data to non-electric component models

- In this workpackage, **specifications on parameters** that need to be determined in order to use the components modeled in WP 3-2 will be written. A feasibility study on how or if the parameters can be determined from experiments will also be conducted. Depending on the feasibility study, modifications on the component modeling might be necessary.

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WP 3-3: Test methods for input data to non-electric component models



- The deliverable from this WP is the specifications of the component parameters.

Flywheel (set_param_flywheel)

```
% HILS parameters for Flywheel
```

```
%-----
```

```
% Jonas Fredriksson
```

```
% Chalmers University of Technology
```

```
% 2012-01-18
```

```
%-----
```

```
%-----
```

```
% Flywheel parameters
```

```
%-----
```

```
J          = 4.7;    % Inertia [kgm^2]
```

```
w_loss_vec_radps = ...    % Index vector for "torque losses" [rad/s]  
    [0 10000 20000];
```

```
T_loss_vec_Nm   = ...    % Torque losses [Nm]  
    [0 10000 20000];
```

Results

- Parameters specified for
 - Flywheel
 - Accumulator
 - Pump/Motor
 - CVT
- Working on: getting relevant data

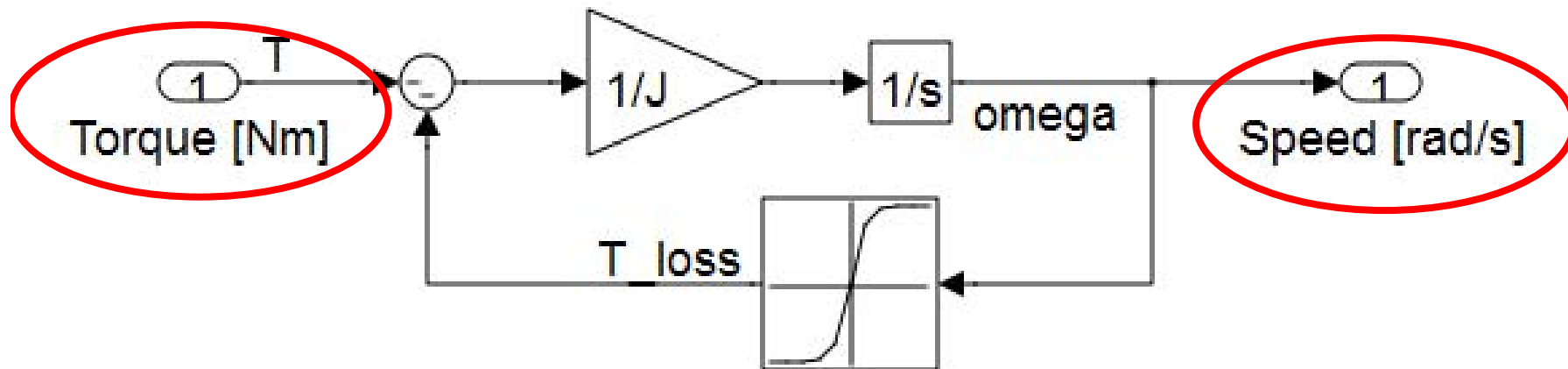
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WP 3-4: Definition of control signals

- Based on the non-electric component models and also available components on the market today determine which **control signals and sensor signals** are necessary/available. Analysis for a standard interface connecting the hardware (HDH ECU) with the HILS software. Identifying the modifications needed to get non-electric hybrid components into the HILS method. This work will be in collaboration with WP 1, see TU Graz and TU Wien offer.

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WP 3-4: Definition of control signals



- The result is a list of input and output signals to and from the non-electric components.
- **Names need to be standardized**
 - Suggestion: (Component_description_unit)

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WP 3-5: Alignment with HILS for HEV and verification

- Review of the HILS method to understand **what modifications are needed** to get the new components into the method. Hypothesis: No major modifications is needed, the non-electric components/subsystems have the same purpose as the electric components/subsystems. Verification of hypothesis.
- Result: Hypothesis is verified or suggestion on modification of method.

Next...

- Implementation
 - MATLAB/Simulink
- Parameterization/Verification (WT 3.3)
 - Data (Need to get real model data from suppliers or OEMs to verify model structure)
- Standardization of variable names (parameter names)
- System modelling (Parallel hydraulic hybrid)
 - Incorporate into the Japanese open-source model
 - Controller design (Started, a simple rule based controller)