

Uncertainty in data processing in R51.03 Annex 10

A basic comparison of the four proposals
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Sources of uncertainty investigated

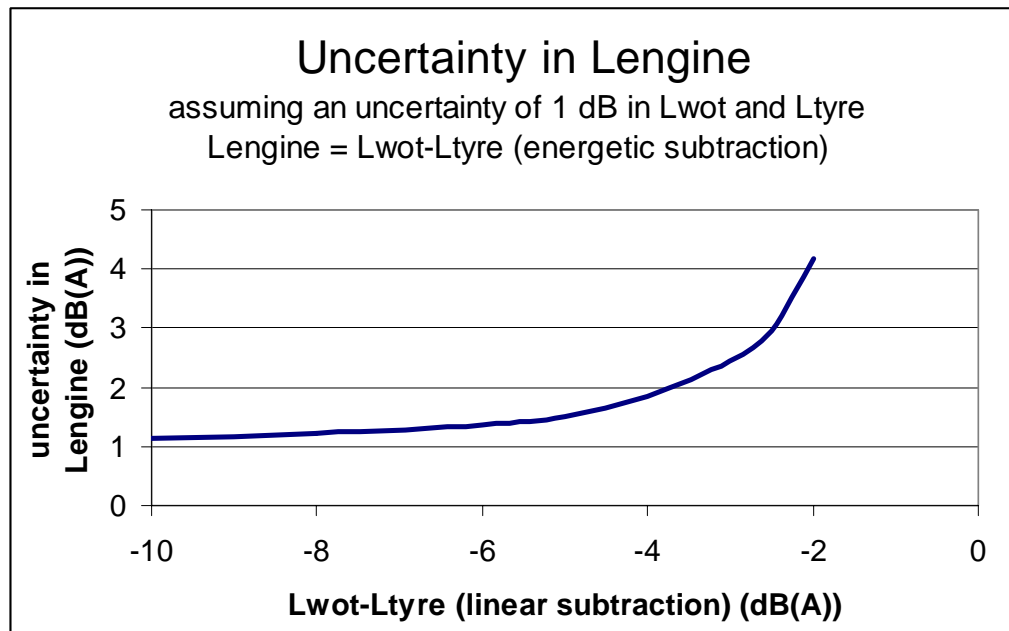
- Measurements
- Calculation
- Limit curve

Uncertainty in noise measurements

- Uncertainty in Annex 3 measurements:
 - Run-run: 0,5 dB(A)
 - Day-day: 0,9 dB(A)
 - Site-site: 1,4 dB(A)
 - (ref: ISO 362)
- Uncertainty in Annex 10 measurements are 2 a 4 times higher.
 - Mainly due to the lack of averaging of measurement results.
 - Uncertainty :: $1/\sqrt{n}$ (n=number of measurements)
 - Annex 3 is the result of 8 to 16 noise measurements.
 - In Annex 10 every single noise measurement is evaluated
 - In 3 of 4 Annex 10 proposals no uncertainty due to acceleration measurements.
Therefore decrease of uncertainty compared to Annex 3
- Conclusion: Uncertainty in Annex 10 measurements
 - Run-run 1,5 dB(A)

Uncertainty due to calculation with noise values

- In case of subtracting noise values, the uncertainty increases
- D/F proposal uses subtraction of noise values. (up to $L_{wot,i} - L_{tyre} = 3$ dB)
- $L_{wot,i}$ and L_{tyre} are assumed to be based on the average of four measurements and to have an uncertainty of each 1 dB(A)
- Uncertainty of L_{engine} is up to 2,5 dB(A)



- Conclusion: D/F proposal uncertainty of reference point = 2,5 dB(A)
- Other options have an uncertainty of the reference point of 1 dB(A)

Uncertainty due to limit curve proposals

- D/F proposal and DeGraaff option have separate limit curves for all gears.
- Japan and Gerhard option are assumed to have a single limit which has to cover the noise variation of 3 different gears
- The extra variation in noise between the 3 gears is assumed to be on average ± 2 dB(A).
- Conclusion: extra uncertainty of single limit proposals: 2 dB(A)

Uncertainty in final noise values

proposal	uncertainty (dB(A))			
	measurements	calculation reference value	limit curve	total
D/F	1,5	2,5	0,0	2,9
Japan	1,5	1,0	2,0	2,7
Graaff	1,5	1,0	0,0	1,8
Gerhard	1,5	1,0	2,0	2,7

Options to decrease uncertainty

- Use averaging of measurement results.
E.g by using regression analysis
- Avoid subtraction of measured (noise) values or set demands to the minimum difference between them
- Match the amount of gears to be judged with the amount of limit curves